

Gauge Invariant Variables in Two-Parameter Nonlinear Perturbations

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(Received March 24, 2003)

The procedure to find gauge invariant variables for two-parameter nonlinear perturbations in general relativity is considered. For each order metric perturbation, we define the variable which is defined by the appropriate combination with lower order metric perturbations. Under the gauge transformation, this variable is transformed in the manner similar to the gauge transformation of the linear order metric perturbation. We confirm this up to third order. This implies that gauge invariant variables for higher order metric perturbations can be found by using a procedure similar to that for linear order metric perturbations. We also derive gauge invariant combinations for the perturbation of an arbitrary physical variable, other than the spacetime metric, up to third order.

§1. Introduction

The perturbative approach is one of the popular techniques to investigate physical systems. In particular, this approach is powerful when the construction of exactly soluble models is difficult. In general relativity, exact solutions to the Einstein equation are most often too idealized to properly represent the realm of natural phenomena, though many exact solutions are known.¹⁾ Here the constructing perturbative solutions around appropriate exact solutions is a useful approach to investigate realistic situations. Cosmological perturbation theory^{2)–4)} is now the most commonly used technique, and perturbations of black holes and stars have been widely studied to obtain descriptions of the gravitational radiation emitted from them.^{5)–7)} These recent perturbative analyses have been extended to second-order perturbations, but in many cases, these treatments employ an expansion in a single parameter.

In some physical applications, it is convenient to introduce two (or more) infinitesimal perturbation parameters to elucidate the physical meaning of the perturbations. One typical example is the study of perturbations of rotating stars.^{8)–10)} No exact analytic stationary axisymmetric solution describing rotating stars has yet been obtained, at least for reasonably interesting equations of state. To treat rotating stars, perturbative analyses employing the “slow rotating approximation” are commonly used. In this approach, the background is a non-rotating star, i.e. spherically symmetric star, and two small parameters, λ and ϵ , corresponding to the pulsation amplitude and the rotation parameter, are introduced. The pulsation amplitude is given by the amplitude of the metric perturbation, and the rotation parameter is given by $\epsilon = \Omega/\sqrt{GM/R^3}$, where Ω is the uniform angular velocity, and M and R

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are the mass and the radius of the non-rotating star, respectively. In this approach, the first order in ϵ describes frame dragging effects, with the star actually remaining spherical, and ϵ^2 terms describe the effects of rotation on the fluid.⁹⁾ Because the mass-shedding limit corresponds to $\epsilon \sim 1$, this approximation is valid for angular velocity Ω much smaller than the mass-shedding limit, and this approximation has also been used recently in the study of the instability in rotating stars. (See the review paper by Stergioulas¹⁰⁾ and references therein). This example shows that the two-parameter perturbation theory is interesting from the viewpoint not only of mathematical physics but also of its applications. There are many astrophysical situations that should be analyzed using multi-parameter perturbation theory.

In spite of these efforts, classical studies in the literature have not been analyzed taking care of the full gauge dependence and gauge invariance of the non-linear perturbation theory. For example, the delicate treatment of gauge freedom is necessary when we evaluate boundary conditions at the surface of the matter distribution and the perturbative displacement of the surface (for example, see Refs. 24)). An implicit fundamental assumption in relativistic perturbation theory is that there exists a parametric family of spacetimes such that the perturbative formalism is built as a Taylor expansion in this family around a background. The perturbations are then defined as the derivative terms of this series, evaluated on this background.¹¹⁾ To carry out this evaluation, we must identify the points on the background spacetime and those on a physical spacetime that we attempt to describe as a perturbation of the background spacetime. This choice of the identification map is usually called the gauge choice.¹²⁾ The important point is that this identification is not unique, i.e. there is a degree of freedom involved in the choice of this identification map. This is the gauge freedom in the perturbation theory. Clearly, this consists of more than the usual assignment of coordinate labels to points of a single spacetime. Further, the Einstein equation does not determine this gauge freedom, and we must fix this gauge freedom by hand or extract the gauge invariant part of the perturbations (for example, see Ref. 13)). This problem does not arise when this gauge freedom is completely fixed and if a change of the gauge is not necessary to analyze or interpret the physical meanings of the results. Otherwise, this problem always arises. Therefore, it is important to clarify the gauge transformation rules of physical variables and the concept of gauge invariance.

In this paper, we present the procedure to define gauge invariant variables in the two-parameter nonlinear perturbation theory. Recently, Bruni and coworkers derived the gauge transformations and introduced the concept of gauge invariance in the two-parameter nonlinear spacetime perturbation theory.¹⁴⁾ They derived explicit gauge transformation rules up to fourth order, i.e., including any term $\lambda^k \epsilon^{k'}$ with $k + k' \leq 4$. We follow their ideas in this paper. Although we keep in mind the above mentioned practical examples, we do not make any specific assumption regarding the background spacetime and the physical meaning of the two-parameter family. Instead, we assume the existence of a procedure to determine the gauge invariant variables at linear order. For each order metric perturbation, we define the variable which is defined by the appropriate combination with lower order metric perturbations. Under the gauge transformation, this variable is transformed in the manner

similar to the gauge transformation of linear order metric perturbation. We confirm this up to third order. This implies that we can always find gauge invariant variables for higher order metric and matter perturbations because we have a procedure to determine gauge invariant variables of linear perturbations as we assumed.

Because we make no assumption concerning the background spacetime, our procedure is applicable to various situations. Further, we note that gauge freedom always exists in the perturbation of theories in which we impose general covariance. Therefore, our procedure is applicable not only to general relativity but also to any theory in which general covariance is imposed. However, we cannot treat the situation in which the change of the differential structure arises due to the perturbations. We also note that the procedure developed here has already been applied to clarify the oscillatory behavior of a gravitating Nambu-Goto string¹³⁾ in which it is crucial to distinguish the gauge freedom of the perturbations and the motion of the string. Through such considerations, we have already confirmed that the procedure we study here is applicable in a specific case.

The organization of this paper is as follows. In §2, we present the necessary mathematical tools, deriving Taylor expansion formulae for two-parameter families of diffeomorphisms. In §3, we set up an appropriate geometrical description of the gauge dependence in two-parameter families of spacetimes and derive gauge transformation rules for the perturbations. In §4, the procedure to determine the gauge invariant variables of nonlinear perturbations is described. The final section, §5, is devoted to summary and discussions. Sections 2 and 3 consists largely of a review of the work of Bruni et al.,¹⁴⁾ which is referred to as BGS2003 in the present paper. However, these sections include some additional explanations that are not given in BGS2003. In particular, we note that the representation of the Taylor expansion given in this paper is simpler but equivalent to that given in BGS2003. We employ the notation of BGS2003 and also use the abstract index notation.¹¹⁾

§2. Taylor expansion of the two parameter diffeomorphisms

Perturbation theories on a manifold are usually based on a Taylor expansion on an extended manifold of the original manifold. Taylor expansions provide an approximation of the value of a quantity at some point in terms of its value and the values of its derivative, at another point. Here, a Taylor expansion of tensorial quantities can only be defined in terms of a mapping between tensors at different points of the manifold under consideration. This implies that a two-parameter perturbation theory on a manifold requires a Taylor expansion of such a mapping given by a two-parameter family of diffeomorphisms on the manifold. In this section, we review the Taylor expansion of two-parameter diffeomorphisms developed in BGS2003, with some modifications to clarify the essence of their idea.

Given a differentiable manifold \mathcal{M} , we consider a family of diffeomorphisms $\Phi_{\lambda,\epsilon}$ characterized by two parameters on \mathcal{M} , λ and ϵ :

$$\begin{aligned} \Phi_{\lambda,\epsilon} : \mathcal{M} \times \mathbb{R}^2 &\rightarrow \mathcal{M} \times \mathbb{R}^2 \\ (p, \lambda, \epsilon) &\mapsto (\Phi_{\lambda,\epsilon}(p), \lambda, \epsilon). \end{aligned} \tag{2.1}$$

As emphasized by Bruni et al.,¹⁵⁾ the diffeomorphisms $\Phi_{\lambda,\epsilon}$ do not form a group in the form $\Phi_{\lambda_1,\epsilon_1} \circ \Phi_{\lambda_2,\epsilon_2} = \Phi_{\lambda_1+\lambda_2,\epsilon_1+\epsilon_2}$ for all $\lambda_i, \epsilon_j \in \mathbb{R}$ ($i = 1, 2$). This differs from the usual situation for exponential maps.¹⁶⁾ In the generic case, we must keep in mind the fact that

$$\Phi_{\lambda_1,\epsilon_1} \circ \Phi_{\lambda_2,\epsilon_2} \neq \Phi_{\lambda_1+\lambda_2,\epsilon_1+\epsilon_2}. \quad (2.2)$$

This means that $\Phi_{\lambda,\epsilon}$, in general, cannot be decomposed into the form $\Phi_{\lambda,\epsilon} = \Phi_{0,\epsilon} \circ \Phi_{\lambda,0}$, where both $\Phi_{0,\epsilon}$ and $\Phi_{\lambda,0}$ are one-parameter families of diffeomorphisms. Hence, in the derivation of the representation of the Taylor expansion of the pull-back $\Phi_{\lambda,\epsilon}^*$ of $\Phi_{\lambda,\epsilon}$, we cannot use the representation of the Taylor expansion of the pull-back of the one-parameter family of diffeomorphisms.^{15),17)} The Taylor expansion based on the usual exponential maps is realized as a special case of the representation derived here.

The simple algebraic properties of the coefficients of the Taylor expansion of $\Phi_{\lambda,\epsilon}^* Q$ for an arbitrary tensor field Q leads to their representation in terms of suitable Lie derivatives. We start from the formal expression of the Taylor expansion of the pull-back $\Phi_{\lambda,\epsilon}^* Q$, which is given by

$$\Phi_{\lambda,\epsilon}^* Q = \sum_{k,k'=0}^{\infty} \frac{\lambda^k \epsilon^{k'}}{k!k'!} \left\{ \frac{\partial^{k+k'}}{\partial \lambda^k \partial \epsilon^{k'}} \Phi_{\lambda,\epsilon}^* Q \right\}_{\lambda=\epsilon=0}. \quad (2.3)$$

As the properties of the coefficients of the Taylor expansion (2.3), we stipulate that the operators $\partial/\partial\lambda$ and $\partial/\partial\epsilon$ in the bracket $\{*\}_{\lambda=\epsilon=0}$ in Eq. (2.3) are not symbolic notation but, rather, the usual partial differential operators on \mathbb{R}^2 . The representation of this Taylor expansion in terms of the Lie derivatives is explicitly derived in Appendix A. We note that the Leibniz rule plays a key role in the derivation of the representation of the Taylor expansion (2.3).

In this paper, we present the expansion of the pull-back $\Phi_{\lambda,\epsilon}^* Q$ to order $\lambda^k \epsilon^{k'}$ with $k + k' = 3$ in terms of suitable Lie derivatives. For this purpose, we introduce the following set of operators $\mathcal{L}_{(p,q)}$, where p and q are integers, on an arbitrary tensor field Q :

$$\mathcal{L}_{(1,0)} Q := \left\{ \frac{\partial}{\partial \lambda} \Phi_{\lambda,\epsilon}^* Q \right\}_{\lambda=\epsilon=0}, \quad (2.4)$$

$$\mathcal{L}_{(0,1)} Q := \left\{ \frac{\partial}{\partial \epsilon} \Phi_{\lambda,\epsilon}^* Q \right\}_{\lambda=\epsilon=0}, \quad (2.5)$$

$$\mathcal{L}_{(2,0)} Q := \left\{ \frac{\partial^2}{\partial \lambda^2} \Phi_{\lambda,\epsilon}^* Q \right\}_{\lambda=\epsilon=0} - \mathcal{L}_{(1,0)}^2 Q, \quad (2.6)$$

$$\mathcal{L}_{(1,1)} Q := \left\{ \frac{\partial^2}{\partial \lambda \partial \epsilon} \Phi_{\lambda,\epsilon}^* Q \right\}_{\lambda=\epsilon=0} - \frac{1}{2} (\mathcal{L}_{(1,0)} \mathcal{L}_{(0,1)} + \mathcal{L}_{(0,1)} \mathcal{L}_{(1,0)}) Q, \quad (2.7)$$

$$\mathcal{L}_{(0,2)} Q := \left\{ \frac{\partial^2}{\partial \epsilon^2} \Phi_{\lambda,\epsilon}^* Q \right\}_{\lambda=\epsilon=0} - \mathcal{L}_{(0,1)}^2 Q, \quad (2.8)$$

$$\mathcal{L}_{(3,0)} Q := \left\{ \frac{\partial^3}{\partial \lambda^3} \Phi_{\lambda,\epsilon}^* Q \right\}_{\lambda=\epsilon=0} - 3\mathcal{L}_{(1,0)} \mathcal{L}_{(2,0)} Q - \mathcal{L}_{(1,0)}^3 Q, \quad (2.9)$$

$$\begin{aligned} \mathcal{L}_{(2,1)}Q := & \left\{ \frac{\partial^3}{\partial \lambda^2 \partial \epsilon} \Phi_{\lambda,\epsilon}^* Q \right\}_{\lambda=\epsilon=0} - 2\mathcal{L}_{(1,0)}\mathcal{L}_{(1,1)}Q - \mathcal{L}_{(0,1)}\mathcal{L}_{(2,0)}Q \\ & - \mathcal{L}_{(1,0)}\mathcal{L}_{(0,1)}\mathcal{L}_{(1,0)}Q, \end{aligned} \quad (2.10)$$

$$\begin{aligned} \mathcal{L}_{(1,2)}Q := & \left\{ \frac{\partial^3}{\partial \lambda \partial \epsilon^2} \Phi_{\lambda,\epsilon}^* Q \right\}_{\lambda=\epsilon=0} - 2\mathcal{L}_{(0,1)}\mathcal{L}_{(1,1)}Q - \mathcal{L}_{(1,0)}\mathcal{L}_{(0,2)}Q \\ & - \mathcal{L}_{(0,1)}\mathcal{L}_{(1,0)}\mathcal{L}_{(0,1)}Q, \end{aligned} \quad (2.11)$$

$$\mathcal{L}_{(0,3)}Q := \left\{ \frac{\partial^3}{\partial \epsilon^3} \Phi_{\lambda,\epsilon}^* Q \right\}_{\lambda=\epsilon=0} - 3\mathcal{L}_{(0,1)}\mathcal{L}_{(0,2)}Q - \mathcal{L}_{(0,1)}^3Q. \quad (2.12)$$

As shown in Appendix A, the above operators $\mathcal{L}_{(p,q)}$ are linear and satisfy the Leibnitz rule, and hence they are derivative operators. Because the pull-back $\Phi_{\lambda,\epsilon}^*$ of a diffeomorphism $\Phi_{\lambda,\epsilon}$ commutes with contractions and the exterior derivative,^{(18),(19)} the operators $\mathcal{L}_{(p,q)}$ also commute with any contraction and exterior derivative. Therefore, for each of them, there is a vector field $\xi_{(p,q)}^a$ such that

$$\mathcal{L}_{\xi_{(p,q)}}Q := \mathcal{L}_{(p,q)}Q \quad (2.13)$$

for $p, q = 0, 1, 2, 3$.

Using the Lie derivative (2.13), we can express the Taylor expansion (2.3) of the pull-back $\Phi_{\lambda,\epsilon}^*$ of $\Phi_{\lambda,\epsilon}$ in terms of the Lie derivatives associated with the vector fields $\xi_{(p,q)}^a$ (2.13) up to third order in λ and ϵ :

$$\begin{aligned} \Phi_{\lambda,\epsilon}^*Q = & Q + \lambda \mathcal{L}_{\xi_{(1,0)}}Q + \epsilon \mathcal{L}_{\xi_{(0,1)}}Q \\ & + \frac{\lambda^2}{2} \left\{ \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}}^2 \right\} Q \\ & + \lambda \epsilon \left\{ \mathcal{L}_{\xi_{(1,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right\} Q \\ & + \frac{\epsilon^2}{2} \left\{ \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}}^2 \right\} Q \\ & + \frac{\lambda^3}{6} \left\{ \mathcal{L}_{\xi_{(3,0)}} + 3\mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}}^3 \right\} Q \\ & + \frac{\lambda^2 \epsilon}{2} \left\{ \mathcal{L}_{\xi_{(2,1)}} + 2\mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(1,1)}} + \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right\} Q \\ & + \frac{\lambda \epsilon^2}{2} \left\{ \mathcal{L}_{\xi_{(1,2)}} + 2\mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,1)}} + \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} \right\} Q \\ & + \frac{\epsilon^3}{6} \left\{ \mathcal{L}_{\xi_{(0,3)}} + 3\mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}}^3 \right\} Q \\ & + O^4(\lambda, \epsilon). \end{aligned} \quad (2.14)$$

Here, we note that the definitions given in Eqs. (2.4)–(2.12) of the derivative operators $\mathcal{L}_{(p,q)}$ and the expression (2.14) of the Taylor expansion does not include arbitrary parameters, while that derived in BGS2003 does. In Appendix A, it is shown that the parameters in the representation derived in BGS2003 can be eliminated through the replacement of the generators $\xi_{(p,q)}^a$ without loss of generality.

The expressions (2.4)–(2.12) and (2.14) are equivalent to those in BGS2003. As emphasized in BGS2003, the representation of the Taylor expansion is not unique, and there are several different but equivalent representations. These representations are reduced to Eq. (2.14) through the replacement of the generators $\xi_{(p,q)}^a$. Henceforth, we refer to the simpler representation (2.14) as the “*canonical representation*” of the Taylor expansion of the two-parameter diffeomorphisms. Further, we denote this expression by $\Phi_{\lambda,\epsilon}^*(\xi_{(p,q)}^a)Q$ when there is a need to specify the generators $\xi_{(p,q)}^a$, explicitly.

Next, we consider the problem how to recover the one-parameter case from the two-parameter case when the two parameters λ and ϵ are no longer independent, e.g. when $\epsilon = \epsilon(\lambda)$. The case in which either λ or ϵ vanishes is trivial and it can be recovered from the above expressions by simply setting $\lambda = 0$ or $\epsilon = 0$. Another simple case in which the two parameters λ and ϵ are linearly dependent, i.e., $\epsilon = a\lambda$ ($a \neq 0$), is discussed in BGS2003, there it is shown that the Taylor expansion of the two-parameter case is reduced to the one-parameter case through the replacement of the generators $\xi_{(p,q)}^a$. Here, we consider the more generic case in which the infinitesimal parameter ϵ is given by a Taylor expansion in λ :

$$\epsilon = \epsilon(\lambda) = \sum_{n=0}^{\infty} a_n \frac{\lambda^n}{n!}. \quad (2.15)$$

Because we only consider the representation $\Phi_{\lambda,\epsilon}^*(\xi_{(p,q)}^a)Q$ to third order, we can restrict our attention to the expression (2.15) up to third order. Substituting (2.15) into the Taylor expansion of $\Phi_{\lambda,\epsilon}^*Q$, we obtain

$$\begin{aligned} \Phi_{\lambda,\epsilon}^*Q &= Q + a_0 \mathcal{L}_{\xi_{(0,1)}} Q + \lambda \mathcal{L}_{\zeta_{(1,0)}} Q \\ &\quad + \frac{1}{2} a_0^2 \left\{ \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}}^2 \right\} Q \\ &\quad + a_0 \lambda \left\{ \mathcal{L}_{\zeta_{(1,1)}} + \frac{1}{2} \mathcal{L}_{\zeta_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\zeta_{(1,0)}} \right\} Q \\ &\quad + \frac{1}{2} \lambda^2 \left\{ \mathcal{L}_{\zeta_{(2,0)}} + \mathcal{L}_{\zeta_{(1,0)}}^2 \right\} Q \\ &\quad + \frac{1}{6} a_0^3 \left\{ \mathcal{L}_{\xi_{(0,3)}} + 3 \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}}^3 \right\} Q \\ &\quad + \frac{1}{2} a_0^2 \lambda \left\{ \mathcal{L}_{\zeta_{(1,2)}} + 2 \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\zeta_{(1,1)}} + \mathcal{L}_{\zeta_{(1,0)}} \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\zeta_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} \right\} Q \\ &\quad + \frac{1}{2} a_0 \lambda^2 \left\{ \mathcal{L}_{\zeta_{(2,1)}} + 2 \mathcal{L}_{\zeta_{(1,0)}} \mathcal{L}_{\zeta_{(1,1)}} + \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\zeta_{(2,0)}} + \mathcal{L}_{\zeta_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\zeta_{(1,0)}} \right\} Q \\ &\quad + \frac{1}{6} \lambda^3 \left\{ \mathcal{L}_{\zeta_{(3,0)}} + 3 \mathcal{L}_{\zeta_{(1,0)}} \mathcal{L}_{\zeta_{(2,0)}} + \mathcal{L}_{\zeta_{(1,0)}}^3 \right\} Q \\ &\quad + O^4(\lambda, a_0), \end{aligned} \quad (2.16)$$

where the vector fields $\zeta_{(p,q)}^a$ are defined by

$$\zeta_{(1,0)}^a := \xi_{(1,0)}^a + a_1 \xi_{(0,1)}^a, \quad (2.17)$$

$$\zeta_{(1,1)}^a := \xi_{(1,1)}^a + a_1 \xi_{(0,2)}^a, \quad (2.18)$$

$$\zeta_{(2,0)}^a := \xi_{(2,0)}^a + 2a_1 \xi_{(1,1)}^a + a_2 \xi_{(0,1)}^a + a_1^2 \xi_{(0,2)}^a, \quad (2.19)$$

$$\zeta_{(1,2)}^a := \xi_{(1,2)}^a + a_1 \xi_{(0,3)}^a, \quad (2.20)$$

$$\zeta_{(2,1)}^a := \xi_{(2,1)}^a + 2a_1 \xi_{(1,2)}^a + a_2 \xi_{(0,2)}^a + a_1^2 \xi_{(0,3)}^a + a_1 [[\xi_{(0,1)}, \xi_{(1,0)}], \xi_{(0,1)}]^a, \quad (2.21)$$

$$\begin{aligned} \zeta_{(3,0)}^a := & \xi_{(3,0)}^a + a_3 \xi_{(0,1)}^a + 3a_2 \xi_{(1,1)}^a + 3a_1 \xi_{(2,1)}^a + 3a_1^2 \xi_{(1,2)}^a \\ & + 3a_2 a_1 \xi_{(0,2)}^a + a_1^3 \xi_{(0,3)}^a + \frac{3}{2} a_2 [\xi_{(0,1)}, \xi_{(1,0)}]^a \\ & + 2a_1^2 [[\xi_{(0,1)}, \xi_{(1,0)}], \xi_{(0,1)}]^a + a_1 [[\xi_{(1,0)}, \xi_{(0,1)}], \xi_{(1,0)}]^a. \end{aligned} \quad (2.22)$$

Equation (2.16) has the form of a Taylor expansion of a diffeomorphism with two infinitesimal parameters, λ and a_0 . Equation (2.16) shows that the coefficient a_0 in the expansion (2.15) plays the role of an infinitesimal perturbation parameter that is independent of λ . When $a_0 = 0$, Eq. (2.16) reduces to the Taylor expansion in the case of a single infinitesimal parameter λ . Thus, even when two infinitesimal parameters depend on each other as in the relation (2.15), we find that the Taylor expansion (2.14) is reduced to that of a single parameter, as in the trivial case $\epsilon = 0$ or $\lambda = 0$.

We next derive the representation of the inverse of the canonical representation $\Phi_{\lambda,\epsilon}^*(\xi_{(p,q)}^a)Q$ for an arbitrary tensor field Q . To do this, we first consider the product $\Psi_{\lambda,\epsilon} \circ \Phi_{\lambda,\epsilon}$ of the two diffeomorphisms $\Psi_{\lambda,\epsilon}$ and $\Phi_{\lambda,\epsilon}$. We consider the canonical representations $\Psi_{\lambda,\epsilon}^*(\zeta_{(p,q)}^a)Q$ and $\Phi_{\lambda,\epsilon}^*(\xi_{(p,q)}^a)Q$. To obtain the Taylor expansion of the pull-back of $\Psi_{\lambda,\epsilon} \circ \Phi_{\lambda,\epsilon}$, we first derive $\Phi_{\lambda,\epsilon}^*(\xi_{(p,q)}^a)S$ for an arbitrary tensor field S and substitute the canonical representation of the Taylor expansion $S = \Psi_{\lambda,\epsilon}^*(\zeta_{(p,q)}^a)Q$. Then, we obtain the representation of the pull-back,

$$\left(\Psi_{\lambda,\epsilon}(\zeta_{(p,q)}^a) \circ \Phi_{\lambda,\epsilon}(\xi_{(p,q)}^a) \right)^* Q = \Phi_{\lambda,\epsilon}^*(\xi_{(p,q)}^a) \circ \Psi_{\lambda,\epsilon}^*(\zeta_{(p,q)}^a)Q. \quad (2.23)$$

In order that we can regard $\Psi_{\lambda,\epsilon}^*(\zeta_{(p,q)}^a)$ as the inverse of $\Phi_{\lambda,\epsilon}^*(\xi_{(p,q)}^a)$, we choose the generators $\zeta_{(p,q)}^a$ so that $\left(\Psi_{\lambda,\epsilon}(\zeta_{(p,q)}^a) \circ \Phi_{\lambda,\epsilon}(\xi_{(p,q)}^a) \right)^* Q = Q$. This is accomplished by choosing

$$\zeta_{(1,0)}^a = -\xi_{(1,0)}^a, \quad (2.24)$$

$$\zeta_{(0,1)}^a = -\xi_{(0,1)}^a, \quad (2.25)$$

$$\zeta_{(2,0)}^a = -\xi_{(2,0)}^a, \quad (2.26)$$

$$\zeta_{(0,2)}^a = -\xi_{(0,2)}^a, \quad (2.27)$$

$$\zeta_{(1,1)}^a = -\xi_{(1,1)}^a, \quad (2.28)$$

$$\zeta_{(3,0)}^a = -\xi_{(3,0)}^a + 3[\xi_{(2,0)}, \xi_{(1,0)}]^a, \quad (2.29)$$

$$\zeta_{(2,1)}^a = -\xi_{(2,1)}^a + [\xi_{(2,0)}, \xi_{(0,1)}]^a + 2[\xi_{(1,1)}, \xi_{(1,0)}]^a, \quad (2.30)$$

$$\zeta_{(1,2)}^a = -\xi_{(1,2)}^a + [\xi_{(0,2)}, \xi_{(1,0)}]^a + 2[\xi_{(1,1)}, \xi_{(0,1)}]^a, \quad (2.31)$$

$$\zeta_{(0,3)}^a = -\xi_{(0,3)}^a + 3[\xi_{(0,2)}, \xi_{(0,1)}]^a. \quad (2.32)$$

Then, the explicit form of $(\Phi_{\lambda,\epsilon}^{-1}(\xi_{(p,q)}^a))^*Q_{\lambda,\epsilon}$ is given by

$$\begin{aligned}
& (\Phi_{\lambda,\epsilon}^{-1}(\xi_{(p,q)}^a))^*Q_{\lambda,\epsilon} \\
&= Q - \lambda \mathcal{L}_{\xi_{(1,0)}} Q - \epsilon \mathcal{L}_{\xi_{(0,1)}} Q \\
&+ \frac{\lambda^2}{2} \left\{ -\mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}}^2 \right\} Q_{\lambda,\epsilon} + \frac{\epsilon^2}{2} \left\{ -\mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}}^2 \right\} Q \\
&+ \lambda \epsilon \left\{ -\mathcal{L}_{\xi_{(1,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right\} Q \\
&+ \frac{\lambda^3}{6} \left\{ -\mathcal{L}_{\xi_{(3,0)}} + 3 \mathcal{L}_{\xi_{(2,0)}} \mathcal{L}_{\xi_{(1,0)}} - \mathcal{L}_{\xi_{(1,0)}}^3 \right\} Q \\
&+ \frac{\lambda^2 \epsilon}{2} \left\{ -\mathcal{L}_{\xi_{(2,1)}} + \mathcal{L}_{\xi_{(2,0)}} \mathcal{L}_{\xi_{(0,1)}} + 2 \mathcal{L}_{\xi_{(1,1)}} \mathcal{L}_{\xi_{(1,0)}} - \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right\} Q \\
&+ \frac{\lambda \epsilon^2}{2} \left\{ -\mathcal{L}_{\xi_{(1,2)}} + \mathcal{L}_{\xi_{(0,2)}} \mathcal{L}_{\xi_{(1,0)}} + 2 \mathcal{L}_{\xi_{(1,1)}} \mathcal{L}_{\xi_{(0,1)}} - \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} \right\} Q \\
&+ \frac{\epsilon^3}{6} \left\{ -\mathcal{L}_{\xi_{(0,3)}} + 3 \mathcal{L}_{\xi_{(0,2)}} \mathcal{L}_{\xi_{(0,1)}} - \mathcal{L}_{\xi_{(0,1)}}^3 \right\} Q + O^4(\lambda, \epsilon). \tag{2.33}
\end{aligned}$$

This explicitly shows that $\Phi_{\lambda,\epsilon}^{-1} \neq \Phi_{-\lambda,-\epsilon}$, as emphasized in BGS2003. Further, if all generators $\xi_{(p,q)}^a$ commute, we obtain the equality $(\Phi_{\lambda,\epsilon}^{-1})^*(\xi_{(p,q)}^a)Q = \Phi_{\lambda,\epsilon}^*(-\xi_{(p,q)}^a)Q$.

Finally, we show that the two-parameter group of diffeomorphisms that satisfy the property

$$\phi_{\lambda_1,\epsilon_1} \circ \phi_{\lambda_2,\epsilon_2} = \phi_{\lambda_1+\lambda_2,\epsilon_1+\epsilon_2} \quad \forall \lambda, \epsilon \in \mathbb{R} \tag{2.34}$$

is obtained as the special case of the two-parameter family of diffeomorphisms. This property implies that the two-parameter group $\phi_{\lambda,\epsilon}$ can be decomposed into two one-parameter groups $\phi_{\lambda,0}$ and $\phi_{0,\epsilon}$ of diffeomorphisms:

$$\phi_{\lambda,\epsilon} = \phi_{\lambda,0} \circ \phi_{0,\epsilon} = \phi_{0,\epsilon} \circ \phi_{\lambda,0}. \tag{2.35}$$

These two one-parameter groups of diffeomorphisms are generated by the vector fields $\eta_{(\lambda)}^a$ and $\eta_{(\epsilon)}^a$, respectively. Each of these vector fields is defined by the action of the corresponding pull-back, $\phi_{\lambda,0}^*$ and $\phi_{0,\epsilon}^*$, for a generic tensor field Q on $\mathcal{M} \times \mathbb{R}$:

$$\mathcal{L}_{\eta_{(\lambda)}} Q := \lim_{\lambda \rightarrow 0} \frac{1}{\lambda} (\phi_{\lambda,0}^* Q - Q), \quad \mathcal{L}_{\eta_{(\epsilon)}} Q := \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} (\phi_{0,\epsilon}^* Q - Q). \tag{2.36}$$

Because the property (2.34) implies that the two-parameter group $\phi_{\lambda,\epsilon}$ is Abelian, the vector field $\eta_{(\lambda)}^a$ and $\eta_{(\epsilon)}^a$ commute

$$[\eta_{(\lambda)}, \eta_{(\epsilon)}]^a = 0. \tag{2.37}$$

The Taylor expansions of the pull-backs $\phi_{\lambda,0}^* T$, $\phi_{0,\epsilon}^* Q$ are given by¹⁵⁾

$$\begin{aligned}
\phi_{\lambda,0}^* Q &= \sum_{k=0}^{\infty} \frac{\lambda^k}{k!} \left[\frac{d^k}{d\lambda^k} \phi_{\lambda,0}^* Q \right]_{\lambda=0} = \sum_{k=0}^{\infty} \frac{\lambda^k}{k!} \mathcal{L}_{\eta_{(\lambda)}}^k Q, \\
\phi_{0,\epsilon}^* Q &= \sum_{k=0}^{\infty} \frac{\epsilon^k}{k!} \left[\frac{d^k}{d\epsilon^k} \phi_{0,\epsilon}^* Q \right]_{\epsilon=0} = \sum_{k=0}^{\infty} \frac{\epsilon^k}{k!} \mathcal{L}_{\eta_{(\epsilon)}}^k Q. \tag{2.38}
\end{aligned}$$

Then, using the decomposition (2.35), we obtain the Taylor expansion of the two-parameter group of pull-backs $\phi_{\lambda,\epsilon}^* Q$:

$$\phi_{\lambda,\epsilon} Q = \sum_{k,k'=0}^{\infty} \frac{\lambda^k \epsilon^{k'}}{k!k'!} \left[\frac{\partial^{k+k'}}{\partial \lambda^k \partial \epsilon^{k'}} \phi_{\lambda,\epsilon}^* Q \right]_{\lambda=\epsilon=0} = \sum_{k,k'=0}^{\infty} \frac{\lambda^k \epsilon^{k'}}{k!k'!} \mathcal{L}_{\eta(\lambda)}^k \mathcal{L}_{\eta(\epsilon)}^{k'} Q. \quad (2.39)$$

This expression is also obtained as the special case of the Taylor expansion (2.14) of the two-parameter family of diffeomorphisms $\Phi_{\lambda,\epsilon}^* Q$ imposing the conditions that $\eta_{(\lambda)}^a = \xi_{(1,0)}^a \neq 0$, $\eta_{(\epsilon)}^a = \xi_{(0,1)}^a \neq 0$, $[\xi_{(1,0)}, \xi_{(0,1)}]^a = 0$, and $\xi_{(p,q)}^a = 0$ for $p+q > 1$.

§3. Gauge transformation of perturbation variables

Using the above Taylor expansion of two-parameter diffeomorphisms, we consider gauge transformations in two-parameter perturbations of the manifold.

3.1. Gauges in perturbation theory

Let us consider the spacetime $(\mathcal{M}_0, {}^{(0)}g_{ab})$, which is the background spacetime for the perturbations, and a physical spacetime (\mathcal{M}, g_{ab}) , which we attempt to describe as a perturbation of the background spacetime $(\mathcal{M}_0, {}^{(0)}g_{ab})$. Let us formally denote the spacetime metric and the other physical tensor fields on the physical spacetime \mathcal{M} by Q . In perturbation theory, we are used to write expressions of the form

$$Q(x) = Q_0(x) + \delta Q(x). \quad (3.1)$$

This expression relates the variable Q on \mathcal{M} to the background value of the same field, Q_0 , and the perturbation δQ . In the expression (3.1), we have implicitly assigned a correspondence between points of the perturbed and the background spacetime. This is the implicit assumption of the existence of a map $\mathcal{M}_0 \rightarrow \mathcal{M} : p \in \mathcal{M}_0 \mapsto q \in \mathcal{M}$.¹²⁾ This correspondence associated with the map $\mathcal{M}_0 \rightarrow \mathcal{M}$ is what is usually called a “gauge choice” in the context of perturbation theory.^{*)} Clearly, this is more than the usual assignment of coordinate labels to points on the single spacetime. It is important to note that the correspondence established by such a relation as Eq. (3.1) is not unique. Rather, Eq. (3.1) involves the degree of freedom corresponding to the choice of the map $\mathcal{M}_0 \rightarrow \mathcal{M}$ (the choice of the point identification map $\mathcal{M}_0 \rightarrow \mathcal{M}$). This is called “gauge freedom”. Further, such freedom always exists in the perturbation of a theory in which we impose general covariance.

Here, we introduce an $(m+2)$ -dimensional manifold \mathcal{N} to study two-parameter perturbation theory based on the above idea. The manifold \mathcal{N} is foliated into m -dimensional submanifolds diffeomorphic to \mathcal{M} , so that $\mathcal{N} = \mathcal{M} \times \mathbb{R}^2$. Each copy of \mathcal{M} is labeled by the corresponding value of the parameters $(\lambda, \epsilon) \in \mathbb{R}^2$. The manifold

^{*)} More precisely, as mentioned in BGS2003, Eq. (3.1) gives a relation between the images of the fields in \mathbb{R}^m rather than between the fields themselves on the respective manifolds \mathcal{M} and \mathcal{M}_0 , i.e., we are saying that there is a unique point $x \in \mathbb{R}$ that is at the same time the image of two points: one in \mathcal{M}_0 and another in \mathcal{M} . However, in this paper, we deal with only the point identification map $\mathcal{X} : \mathcal{M}_0 \rightarrow \mathcal{M}$.

\mathcal{N} has a natural differentiable structure that is the direct product of that of \mathcal{M} and \mathbb{R}^2 . With this construction, the perturbed spacetimes $\mathcal{M}_{\lambda,\epsilon}$ for each (λ, ϵ) must have the same differential structure, and the changes of the differential structure resulting from the perturbation, for example the formation of singularities, is excluded from our consideration. Each point on \mathcal{N} is assigned by (p, λ, ϵ) , where $p \in \mathcal{M}_{\lambda,\epsilon}$, and each point on the background spacetime \mathcal{M}_0 in \mathcal{N} is assigned by $\lambda = \epsilon = 0$.

Let us consider the set of field equations

$$\mathcal{E}[Q_{\lambda,\epsilon}] = 0 \quad (3.2)$$

on $\mathcal{M}_{\lambda,\epsilon}$ for the physical variables Q on $\mathcal{M}_{\lambda,\epsilon}$. The field equation (3.2) formally represents the Einstein equation for the metric on $\mathcal{M}_{\lambda,\epsilon}$ and the field equations for matter fields on $\mathcal{M}_{\lambda,\epsilon}$. If a tensor field $Q_{\lambda,\epsilon}$ is given on each $\mathcal{M}_{\lambda,\epsilon}$, $Q_{\lambda,\epsilon}$ is automatically extended to a tensor field on \mathcal{N} by $Q(p, \lambda, \epsilon) := Q_{\lambda,\epsilon}(p)$, with $p \in \mathcal{M}_{\lambda,\epsilon}$. In this extension, the field equation (3.2) is regarded as the equation on \mathcal{N} .

Now, we define the perturbation for an arbitrary tensor field Q by comparing $Q_{\lambda,\epsilon}$ with Q_0 . To do this, it is necessary to identify the points of $\mathcal{M}_{\lambda,\epsilon}$ with those of \mathcal{M}_0 . This is easily accomplished by assigning a diffeomorphism $\mathcal{X}_{\lambda,\epsilon} : \mathcal{N} \rightarrow \mathcal{N}$ such that $\mathcal{X}_{\lambda,\epsilon} : \mathcal{M}_0 \rightarrow \mathcal{M}_{\lambda,\epsilon}$. It is natural to regard $\mathcal{X}_{\lambda,\epsilon}$ as one of the two-parameter group of diffeomorphisms that satisfy the property (2.34). Then, $\mathcal{X}_{\lambda,\epsilon}$ is generated by two vector fields ${}^{\mathcal{X}}\eta_{(\lambda)}^a$ and ${}^{\mathcal{X}}\eta_{(\epsilon)}^a$ on \mathcal{N} that satisfy

$$[{}^{\mathcal{X}}\eta_{(\lambda)}, {}^{\mathcal{X}}\eta_{(\epsilon)}]^a = 0. \quad (3.3)$$

Further, the normal forms of $\mathcal{M}_{\lambda,\epsilon}$ in \mathcal{N} are given by $(d\lambda)_a$ and $(d\epsilon)_a$, and their duals are defined by

$$\left(\frac{\partial}{\partial\lambda}\right)^a (d\lambda)_a = 1, \quad \left(\frac{\partial}{\partial\epsilon}\right)^a (d\epsilon)_a = 1, \quad \left(\frac{\partial}{\partial\lambda}\right)^a (d\epsilon)_a = 0, \quad \left(\frac{\partial}{\partial\epsilon}\right)^a (d\lambda)_a = 0. \quad (3.4)$$

The vector fields ${}^{\mathcal{X}}\eta_{(\lambda)}^a$ and ${}^{\mathcal{X}}\eta_{(\epsilon)}^a$ are chosen so that

$${}^{\mathcal{X}}\eta_{(\lambda)}^a = \left(\frac{\partial}{\partial\lambda}\right)^a + \theta_{(\lambda)}^a, \quad {}^{\mathcal{X}}\eta_{(\epsilon)}^a = \left(\frac{\partial}{\partial\epsilon}\right)^a + \theta_{(\epsilon)}^a, \quad (3.5)$$

where $\theta_{(\lambda)}^a$ and $\theta_{(\epsilon)}^a$ are tangent to $\mathcal{M}_{\lambda,\epsilon}$ for each λ and ϵ :

$$\theta_{(\lambda),(\epsilon)}^a (d\epsilon)_a = \theta_{(\lambda),(\epsilon)}^a (d\lambda)_a = 0. \quad (3.6)$$

The choice of the vector fields $\theta_{(\lambda),(\epsilon)}^a$ is essentially arbitrary, except for the conditions (3.3) and (3.6). Therefore, we choose $\theta_{(\lambda),(\epsilon)}^a$ so that

$$\mathcal{L}_{\frac{\partial}{\partial\lambda}} \theta_{(\lambda),(\epsilon)}^a = \mathcal{L}_{\frac{\partial}{\partial\epsilon}} \theta_{(\epsilon),(\lambda)}^a = 0 \quad (3.7)$$

for simplicity. Except for these conditions, we can regard $\theta_{(\lambda),(\epsilon)}^a$ as essentially arbitrary vector fields on $\mathcal{M}_{\lambda,\epsilon}$ (not on \mathcal{N}) that all commute.

The perturbation $\Delta_0^{\mathcal{X}} Q_{\lambda,\epsilon}$ of a tensor field Q for a gauge choice \mathcal{X} can now be defined simply as

$$\Delta_0^{\mathcal{X}} Q_{\lambda,\epsilon} := \mathcal{X}_{\lambda,\epsilon}^* Q|_{\mathcal{M}_0} - Q_0. \quad (3.8)$$

The first term on the right-hand side of (3.8) can be Taylor-expanded as

$$\mathcal{X}_{\lambda,\epsilon}^* Q|_{\mathcal{M}_0} = \sum_{k,k'=0}^{\infty} \frac{\lambda^k \epsilon^{k'}}{k!k'!} \delta_{\mathcal{X}}^{(k,k')} Q, \quad (3.9)$$

where

$$\delta_{\mathcal{X}}^{(k,k')} Q := \left[\frac{\partial^{k+k'}}{\partial \lambda^k \partial \epsilon^{k'}} \mathcal{X}_{\lambda,\epsilon}^* Q \right]_{\lambda=\epsilon=0} = \mathcal{L}_{\mathcal{X}_{\eta_{\lambda}}}^k \mathcal{L}_{\mathcal{X}_{\eta_{\epsilon}}}^{k'} Q|_{\mathcal{M}_0}. \quad (3.10)$$

Equations (3.8)–(3.10) define the perturbation of order (k, k') of a physical variable Q for the gauge choice \mathcal{X} and its background value $\delta_{\mathcal{X}}^{(0,0)} Q = Q_0$.

3.2. Gauge invariance and gauge transformations

Let us now suppose that two gauges \mathcal{X} and \mathcal{Y} are generated by the pairs of vector fields $(\mathcal{X}_{\eta_{(\lambda)}}, \mathcal{X}_{\eta_{(\epsilon)}})$ and $(\mathcal{Y}_{\eta_{(\lambda)}}, \mathcal{Y}_{\eta_{(\epsilon)}})$, respectively. These vector field are defined on \mathcal{N} as the vector fields in Eqs. (3.5) :

$$\mathcal{X}_{\eta_{(\lambda)}}^a = \left(\frac{\partial}{\partial \lambda} \right)^a + \theta_{(\lambda)}^a, \quad \mathcal{X}_{\eta_{(\epsilon)}}^a = \left(\frac{\partial}{\partial \epsilon} \right)^a + \theta_{(\epsilon)}^a, \quad (3.11)$$

$$\mathcal{Y}_{\eta_{(\lambda)}}^a = \left(\frac{\partial}{\partial \lambda} \right)^a + \iota_{(\lambda)}^a, \quad \mathcal{Y}_{\eta_{(\epsilon)}}^a = \left(\frac{\partial}{\partial \epsilon} \right)^a + \iota_{(\epsilon)}^a. \quad (3.12)$$

The condition (3.3) for each set of generators, $\mathcal{X}_{\eta_{(\lambda),(\epsilon)}}^a$ and $\mathcal{Y}_{\eta_{(\lambda),(\epsilon)}}^a$, implies that the two-dimensional tangent space spanned by $\mathcal{X}_{\eta_{(\lambda),(\epsilon)}}^a$ ($\mathcal{Y}_{\eta_{(\lambda),(\epsilon)}}^a$) possesses a two-dimensional integral surface. These integral surfaces of $\mathcal{X}_{\eta_{(\lambda),(\epsilon)}}^a$ and $\mathcal{Y}_{\eta_{(\lambda),(\epsilon)}}^a$ define two two-parameter groups of diffeomorphisms \mathcal{X} and \mathcal{Y} on \mathcal{N} . Further, $\mathcal{X}_{\eta_{(\lambda),(\epsilon)}}^a$ and $\mathcal{Y}_{\eta_{(\lambda),(\epsilon)}}^a$ are everywhere transverse to $\mathcal{M}_{\lambda,\epsilon}$, and points lying on the same integral surface of either of the two are to be regarded as *the same point* within the respective gauge. (See Fig. 1.) Then, \mathcal{X} and \mathcal{Y} are both point identification maps. When $\theta_{(\lambda),(\epsilon)}^a \neq \iota_{(\lambda),(\epsilon)}^a$, these point identification maps are regarded as two different gauge choices.

The pairs of vector fields $\mathcal{X}_{\eta_{(\lambda),(\epsilon)}}^a$ and $\mathcal{Y}_{\eta_{(\lambda),(\epsilon)}}^a$ are both generators of two-parameter groups of diffeomorphisms, and they pull back a generic tensor Q to two other tensor fields, $\mathcal{X}_{\lambda,\epsilon}^* Q$ and $\mathcal{Y}_{\lambda,\epsilon}^* Q$, for any given value of (λ, ϵ) . In particular, on \mathcal{M}_0 , we now have three tensor fields, i.e. Q_0 and the following two :

$$\mathcal{X} Q_{\lambda,\epsilon} := \mathcal{X}_{\lambda,\epsilon}^* Q|_{\mathcal{M}_0}, \quad \mathcal{Y} Q_{\lambda,\epsilon} := \mathcal{Y}_{\lambda,\epsilon}^* Q|_{\mathcal{M}_0}. \quad (3.13)$$

Because \mathcal{X} and \mathcal{Y} represent gauge choices mapping the background spacetime \mathcal{M}_0 into a perturbed manifold $\mathcal{M}_{\lambda,\epsilon}$, as mentioned above, $\mathcal{X} Q_{\lambda,\epsilon}$ and $\mathcal{Y} Q_{\lambda,\epsilon}$ are the representations in \mathcal{M}_0 of the perturbed tensor for the two gauges. Using (3.8)–(3.10),

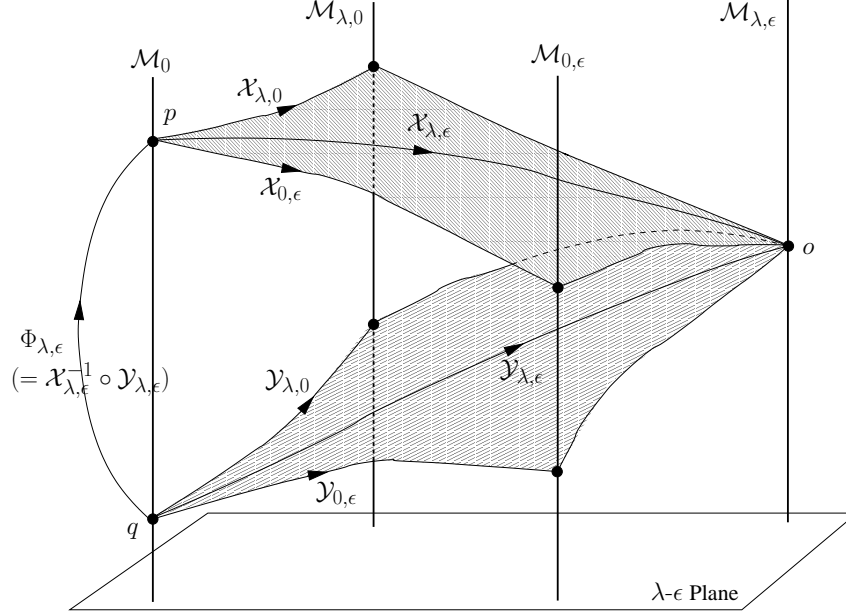


Fig. 1. Point identification from the background manifold to the perturbed manifold.

we can write

$$\mathcal{X}Q_{\lambda,\epsilon} = \sum_{k,k'=0}^{\infty} \frac{\lambda^k \epsilon^{k'}}{k!k'!} \delta_{\mathcal{X}}^{(k,k')} Q = Q_0 + \Delta_0^{\mathcal{X}} Q_{\lambda,\epsilon}, \quad (3.14)$$

$$\mathcal{Y}Q_{\lambda,\epsilon} = \sum_{k,k'=0}^{\infty} \frac{\lambda^k \epsilon^{k'}}{k!k'!} \delta_{\mathcal{Y}}^{(k,k')} Q = Q_0 + \Delta_0^{\mathcal{Y}} Q_{\lambda,\epsilon}, \quad (3.15)$$

where $\delta_{\mathcal{X}}^{(k,k')} Q$, and $\delta_{\mathcal{Y}}^{(k,k')} Q$ are the perturbations (3.10) in the gauges \mathcal{X} and \mathcal{Y} , respectively ;

$$\delta_{\mathcal{X}}^{(k,k')} Q = \mathcal{L}_{\mathcal{X}_{\eta(\lambda)}}^k \mathcal{L}_{\mathcal{X}_{\eta(\epsilon)}}^{k'} Q \Big|_{\mathcal{M}_0}, \quad \delta_{\mathcal{Y}}^{(k,k')} Q = \mathcal{L}_{\mathcal{Y}_{\eta(\lambda)}}^k \mathcal{L}_{\mathcal{Y}_{\eta(\epsilon)}}^{k'} Q \Big|_{\mathcal{M}_0}. \quad (3.16)$$

Following Bruni et al.,¹⁴⁾ we consider the concept of *gauge invariance up to order* (n, n') . We say that Q is *gauge invariant up to order* (n, n') iff for any two gauges \mathcal{X} and \mathcal{Y}

$$\delta_{\mathcal{X}}^{(k,k')} Q = \delta_{\mathcal{Y}}^{(k,k')} Q \quad \forall (k, k'), \quad \text{with } k < n, \quad k' < n'. \quad (3.17)$$

From this definition, we can prove that the (n, n') -order perturbation of a tensor field Q is gauge invariant up to order (n, n') iff in a given gauge \mathcal{X} we have $\mathcal{L}_{\xi}^{\mathcal{X}} \delta^{(k,k')} Q = 0$ for any vector field ξ^a defined on \mathcal{M}_0 and for any $(k, k') < (n, n')$. As a consequence, the (n, n') -order perturbation of a tensor field Q is gauge invariant up to order (n, n') iff Q_0 and all its perturbations of lower than (n, n') order are, in any gauge, either vanishing or constant scalars, or a combination of Kronecker deltas with constant coefficients.^{12), 14), 15)}

Next, we consider the gauge transformation of a tensor field Q . If a tensor Q is not gauge invariant, its representation on \mathcal{M}_0 does change under a gauge transformation. To consider the change under a gauge transformation, we introduce the diffeomorphism $\Phi_{\lambda,\epsilon} : \mathcal{M}_0 \rightarrow \mathcal{M}_0$ for each value of $(\lambda, \epsilon) \in \mathbb{R}^2$. The diffeomorphism $\Phi_{\lambda,\epsilon}$ is defined by

$$\Phi_{\lambda,\epsilon} := (\mathcal{X}_{\lambda,\epsilon})^{-1} \circ \mathcal{Y}_{\lambda,\epsilon} = \mathcal{X}_{-\lambda,-\epsilon} \circ \mathcal{Y}_{\lambda,\epsilon}, \quad (3.18)$$

where we have used the fact that the point identification map \mathcal{X} is a two-parameter group of diffeomorphism. When \mathcal{X} and \mathcal{Y} are regarded as two different gauge choices, $\Phi_{\lambda,\epsilon}$ represents the gauge transformation from the gauge \mathcal{X} to the gauge \mathcal{Y} . It is important to note that as a consequence of the definition (3.18), $\Phi_{\lambda,\epsilon} : \mathcal{M}_0 \times \mathbb{R}^2 \rightarrow \mathcal{M}_0$ does *not* become a two-parameter group of diffeomorphisms in \mathcal{M}_0 , while the identification maps \mathcal{X} and \mathcal{Y} are both two-parameter group of diffeomorphisms. Actually, $\Phi_{\lambda_1,\epsilon_1} \circ \Phi_{\lambda_2,\epsilon_2} \neq \Phi_{\lambda_1+\lambda_2,\epsilon_1+\epsilon_2}$, due to the fact that the vector fields ${}^{\mathcal{X}}\eta_{(\lambda),(\epsilon)}^a$ and ${}^{\mathcal{Y}}\eta_{(\lambda),(\epsilon)}^a$ have, in general, a non-vanishing commutator. In spite that $\Phi_{\lambda,\epsilon}$ is not a two-parameter group of diffeomorphisms, the representation of the Taylor expansion of the pull-back $\Phi_{\lambda,\epsilon}^* Q$ for an arbitrary tensor field Q is obtained by using the results of §2.

The tensor fields ${}^{\mathcal{X}}Q_{\lambda,\epsilon}$ and ${}^{\mathcal{Y}}Q_{\lambda,\epsilon}$, which are defined on \mathcal{M}_0 by the gauges \mathcal{X} and \mathcal{Y} , are connected by the linear map $\Phi_{\lambda,\epsilon}^*$ as

$$\begin{aligned} {}^{\mathcal{Y}}Q_{\lambda,\epsilon} &= \mathcal{Y}_{\lambda,\epsilon}^* Q|_{\mathcal{M}_0} = (\mathcal{Y}_{\lambda,\epsilon}^* \mathcal{X}_{-\lambda,-\epsilon}^* {}^{\mathcal{X}}Q)|_{\mathcal{M}_0} \\ &= \Phi_{\lambda,\epsilon}^* ({}^{\mathcal{X}}Q_{\lambda,\epsilon})|_{\mathcal{M}_0} = \Phi_{\lambda,\epsilon}^* {}^{\mathcal{X}}Q_{\lambda,\epsilon}. \end{aligned} \quad (3.19)$$

Therefore, the gauge transformation to an arbitrary order (n, n') is given by the Taylor expansion of the pull-back $\Phi_{\lambda,\epsilon}^* Q$, whose terms are explicitly given in §2. Up to third order, the explicit form of the Taylor expansion is given by

$$\begin{aligned} \Phi_{\lambda,\epsilon}^* Q &= Q + \lambda \mathcal{L}_{\xi_{(1,0)}} Q + \epsilon \mathcal{L}_{\xi_{(0,1)}} Q \\ &\quad + \frac{\lambda^2}{2} \left\{ \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}}^2 \right\} Q \\ &\quad + \lambda \epsilon \left\{ \mathcal{L}_{\xi_{(1,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right\} Q \\ &\quad + \frac{\epsilon^2}{2} \left\{ \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}}^2 \right\} Q \\ &\quad + \frac{\lambda^3}{6} \left\{ \mathcal{L}_{\xi_{(3,0)}} + 3 \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}}^3 \right\} Q \\ &\quad + \frac{\lambda^2 \epsilon}{2} \left\{ \mathcal{L}_{\xi_{(2,1)}} + 2 \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(1,1)}} + \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right\} Q \\ &\quad + \frac{\lambda \epsilon^2}{2} \left\{ \mathcal{L}_{\xi_{(1,2)}} + 2 \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,1)}} + \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} \right\} Q \\ &\quad + \frac{\epsilon^3}{6} \left\{ \mathcal{L}_{\xi_{(0,3)}} + 3 \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}}^3 \right\} Q \\ &\quad + O^4(\lambda, \epsilon), \end{aligned} \quad (3.20)$$

using the canonical representation (2.14) of $\Phi_{\lambda,\epsilon}^*(\xi_{(p,q)}^a)$, where $\xi_{(p,q)}$ are now the generators of the gauge transformation $\Phi_{\lambda,\epsilon}$.

Comparing the representation (3.20) of the expansion in terms of the generators $\xi_{(p,q)}$ of the pull-back $\Phi_{\lambda,\epsilon}^*Q$ and that in terms of the generators ${}^{\mathcal{X}}\eta_{(\lambda),(\epsilon)}^a$ and ${}^{\mathcal{Y}}\eta_{(\lambda),(\epsilon)}^a$ of the pull-back $\mathcal{Y}_{\lambda,\epsilon}^* \circ \mathcal{X}_{-\lambda,-\epsilon}^*Q (= \Phi_{\lambda,\epsilon}^*Q)$, we find explicit expressions for the generators $\xi_{(p,q)}^a$ of the gauge transformation $\Phi = \mathcal{X}^{-1} \circ \mathcal{Y}$ in terms of the gauge vector fields ${}^{\mathcal{X}}\eta_{(\lambda),(\epsilon)}^a$ and ${}^{\mathcal{Y}}\eta_{(\lambda),(\epsilon)}^a$. Here, we give their expressions up to third order:

$$\begin{aligned}\xi_{(1,0)}^a &= {}^{\mathcal{Y}}\eta_{(\lambda)}^a - {}^{\mathcal{X}}\eta_{(\lambda)}^a \\ &= \iota_{(\lambda)}^a - \theta_{(\lambda)}^a,\end{aligned}\tag{3.21}$$

$$\begin{aligned}\xi_{(0,1)}^a &= {}^{\mathcal{Y}}\eta_{(\epsilon)}^a - {}^{\mathcal{X}}\eta_{(\epsilon)}^a \\ &= \iota_{(\epsilon)}^a - \theta_{(\epsilon)}^a,\end{aligned}\tag{3.22}$$

$$\begin{aligned}\xi_{(2,0)}^a &= [{}^{\mathcal{X}}\eta_{(\lambda)}, {}^{\mathcal{Y}}\eta_{(\lambda)}]^a \\ &= [\theta_{(\lambda)}, \iota_{(\lambda)}]^a,\end{aligned}\tag{3.23}$$

$$\begin{aligned}\xi_{(1,1)}^a &= \frac{1}{2}[{}^{\mathcal{X}}\eta_{(\lambda)}, {}^{\mathcal{Y}}\eta_{(\epsilon)}]^a + \frac{1}{2}[{}^{\mathcal{X}}\eta_{(\epsilon)}, {}^{\mathcal{Y}}\eta_{(\lambda)}]^a \\ &= \frac{1}{2}[\theta_{(\lambda)}, \iota_{(\epsilon)}]^a + \frac{1}{2}[\theta_{(\epsilon)}, \iota_{(\lambda)}]^a,\end{aligned}\tag{3.24}$$

$$\begin{aligned}\xi_{(0,2)}^a &= [{}^{\mathcal{X}}\eta_{(\epsilon)}, {}^{\mathcal{Y}}\eta_{(\epsilon)}]^a \\ &= [\theta_{(\epsilon)}, \iota_{(\epsilon)}]^a,\end{aligned}\tag{3.25}$$

$$\begin{aligned}\xi_{(3,0)}^a &= [[{}^{\mathcal{X}}\eta_{(\lambda)}, {}^{\mathcal{Y}}\eta_{(\lambda)}], {}^{\mathcal{Y}}\eta_{(\lambda)} - 2{}^{\mathcal{X}}\eta_{(\lambda)}]^a \\ &= [[\theta_{(\lambda)}, \iota_{(\lambda)}], \iota_{(\lambda)} - 2\theta_{(\lambda)}]^a,\end{aligned}\tag{3.26}$$

$$\begin{aligned}\xi_{(2,1)}^a &= [[{}^{\mathcal{Y}}\eta_{(\lambda)}, {}^{\mathcal{X}}\eta_{(\epsilon)}], {}^{\mathcal{X}}\eta_{(\lambda)}]^a + [[{}^{\mathcal{X}}\eta_{(\lambda)}, {}^{\mathcal{Y}}\eta_{(\epsilon)}], {}^{\mathcal{Y}}\eta_{(\lambda)} - {}^{\mathcal{X}}\eta_{(\lambda)}]^a \\ &= [[\iota_{(\lambda)}, \theta_{(\epsilon)}], \theta_{(\lambda)}]^a + [[\theta_{(\lambda)}, \iota_{(\epsilon)}], \iota_{(\lambda)} - \theta_{(\lambda)}]^a,\end{aligned}\tag{3.27}$$

$$\begin{aligned}\xi_{(1,2)}^a &= [[{}^{\mathcal{Y}}\eta_{(\epsilon)}, {}^{\mathcal{X}}\eta_{(\epsilon)}], {}^{\mathcal{X}}\eta_{(\lambda)}]^a + [[{}^{\mathcal{X}}\eta_{(\epsilon)}, {}^{\mathcal{Y}}\eta_{(\epsilon)}], {}^{\mathcal{Y}}\eta_{(\epsilon)} - {}^{\mathcal{X}}\eta_{(\epsilon)}]^a \\ &= [[\iota_{(\epsilon)}, \theta_{(\epsilon)}], \theta_{(\lambda)}]^a + [[\theta_{(\epsilon)}, \iota_{(\epsilon)}], \iota_{(\epsilon)} - \theta_{(\epsilon)}]^a,\end{aligned}\tag{3.28}$$

$$\begin{aligned}\xi_{(0,3)}^a &= [[{}^{\mathcal{X}}\eta_{(\epsilon)}, {}^{\mathcal{Y}}\eta_{(\epsilon)}], {}^{\mathcal{Y}}\eta_{(\epsilon)} - 2{}^{\mathcal{X}}\eta_{(\epsilon)}]^a \\ &= [[\theta_{(\epsilon)}, \iota_{(\epsilon)}], \iota_{(\epsilon)} - 2\theta_{(\epsilon)}]^a.\end{aligned}\tag{3.29}$$

The expression (3.24) of the generator $\xi_{(1,1)}^a$ is different from that derived in BGS2003. This is due to the difference between the representations of the Taylor expansion of the pull-back $\Phi_{\lambda,\epsilon}^*Q$. In the perturbation theory, these expressions, (3.21)–(3.29), are evaluated on the background spacetime \mathcal{M}_0 . Then, these expressions show explicitly that the generators $\xi_{(p,q)}^a$ of the gauge transformation $\Phi_{\lambda,\epsilon} = \mathcal{X}^{-1} \circ \mathcal{Y}$ are vector fields on the background \mathcal{M}_0 . Further, Eqs. (3.23)–(3.29) show that the generators $\xi_{(p,q)}^a$ with $p+q > 1$ naturally arise from the non-commutativity of the gauge generators ${}^{\mathcal{X}}\eta_{(\lambda),(\epsilon)}^a$ and ${}^{\mathcal{Y}}\eta_{(\lambda),(\epsilon)}^a$.

We can now derive the relation between the perturbations in the two different gauges. Up to order (n, n') with $n + n' \leq 3$, these relations can be derived by

substituting (3.14) and (3.15) into (3.20):

$$\delta_y^{(1,0)} Q - \delta_{\mathcal{X}}^{(1,0)} Q = \mathcal{L}_{\xi_{(1,0)}} Q_0, \quad (3.30)$$

$$\delta_y^{(0,1)} Q - \delta_{\mathcal{X}}^{(0,1)} Q = \mathcal{L}_{\xi_{(0,1)}} Q_0, \quad (3.31)$$

$$\delta_y^{(2,0)} Q - \delta_{\mathcal{X}}^{(2,0)} Q = 2\mathcal{L}_{\xi_{(1,0)}} \delta_{\mathcal{X}}^{(1,0)} Q + \left\{ \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}}^2 \right\} Q_0, \quad (3.32)$$

$$\begin{aligned} \delta_y^{(1,1)} Q - \delta_{\mathcal{X}}^{(1,1)} Q &= \mathcal{L}_{\xi_{(1,0)}} \delta_{\mathcal{X}}^{(0,1)} Q + \mathcal{L}_{\xi_{(0,1)}} \delta_{\mathcal{X}}^{(1,0)} Q \\ &\quad + \left\{ \mathcal{L}_{\xi_{(1,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right\} Q_0, \end{aligned} \quad (3.33)$$

$$\delta_y^{(0,2)} Q - \delta_{\mathcal{X}}^{(0,2)} Q = 2\mathcal{L}_{\xi_{(0,1)}} \delta_{\mathcal{X}}^{(0,1)} Q + \left\{ \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}}^2 \right\} Q_0, \quad (3.34)$$

$$\begin{aligned} \delta_y^{(3,0)} Q - \delta_{\mathcal{X}}^{(3,0)} Q &= 3\mathcal{L}_{\xi_{(1,0)}} \delta_{\mathcal{X}}^{(2,0)} Q + 3 \left\{ \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}}^2 \right\} \delta_{\mathcal{X}}^{(1,0)} Q \\ &\quad + \left\{ \mathcal{L}_{\xi_{(3,0)}} + 3\mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}}^3 \right\} Q_0, \end{aligned} \quad (3.35)$$

$$\begin{aligned} \delta_y^{(2,1)} Q - \delta_{\mathcal{X}}^{(2,1)} Q &= 2\mathcal{L}_{\xi_{(1,0)}} \delta_{\mathcal{X}}^{(1,1)} Q + \mathcal{L}_{\xi_{(0,1)}} \delta_{\mathcal{X}}^{(2,0)} Q \\ &\quad + \left\{ \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}}^2 \right\} \delta_{\mathcal{X}}^{(0,1)} Q \\ &\quad + 2 \left\{ \mathcal{L}_{\xi_{(1,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right\} \delta_{\mathcal{X}}^{(1,0)} Q \\ &\quad + \left\{ \mathcal{L}_{\xi_{(2,1)}} + 2\mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(1,1)}} + \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(2,0)}} \right. \\ &\quad \left. + \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right\} Q_0, \end{aligned} \quad (3.36)$$

$$\begin{aligned} \delta_y^{(1,2)} Q - \delta_{\mathcal{X}}^{(1,2)} Q &= 2\mathcal{L}_{\xi_{(0,1)}} \delta_{\mathcal{X}}^{(1,1)} Q + \mathcal{L}_{\xi_{(1,0)}} \delta_{\mathcal{X}}^{(0,2)} Q \\ &\quad + \left\{ \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}}^2 \right\} \delta_{\mathcal{X}}^{(1,0)} Q \\ &\quad + 2 \left\{ \mathcal{L}_{\xi_{(1,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right\} \delta_{\mathcal{X}}^{(0,1)} Q \\ &\quad + \left\{ \mathcal{L}_{\xi_{(1,2)}} + 2\mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,1)}} + \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,2)}} \right. \\ &\quad \left. + \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} \right\} Q_0, \end{aligned} \quad (3.37)$$

$$\begin{aligned} \delta_y^{(0,3)} Q - \delta_{\mathcal{X}}^{(0,3)} Q &= 3\mathcal{L}_{\xi_{(0,1)}} \delta_{\mathcal{X}}^{(0,2)} Q + 3 \left\{ \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}}^2 \right\} \delta_{\mathcal{X}}^{(0,1)} Q \\ &\quad + \left\{ \mathcal{L}_{\xi_{(0,3)}} + 3\mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}}^3 \right\} Q_0. \end{aligned} \quad (3.38)$$

These results are, of course, consistent with the gauge invariance up to order (n, n') as introduced above. Equation (3.30) [or (3.31)] implies that $Q_{\lambda, \epsilon}$ is gauge invariant up to order $(1, 0)$ [or $(0, 1)$] iff $\mathcal{L}_{\xi} Q_0 = 0$ for any vector field ξ^a on \mathcal{M}_0 . Equation (3.32) implies that $Q_{\lambda, \epsilon}$ is gauge invariant up to order $(2, 0)$ iff $\mathcal{L}_{\xi} Q_0 = 0$ and $\mathcal{L}_{\xi} \delta_{\mathcal{X}}^{(1,0)} Q_0 = 0$ for any vector field on \mathcal{M}_0 . This can be repeated analogously for all the orders.

3.3. Coordinate transformations

The above formulation of the perturbations and their gauge transformation are independent of the explicit form of the coordinate system. In some situations, it is convenient to introduce an explicit coordinate system in order to carry out explicit calculations in a practical case. Then, it is instructive to show the above geometrical formulation of gauge transformations in terms of the corresponding coordinate transformations, though it is not necessary for the discussion in §§4 and 5. Here, we briefly discuss this coordinate transformation. The explicit forms of this transformation given below show the fact that the gauge freedom in perturbation theory is more than the usual assignment of coordinate labels to points on the single space-time. Details of the outline given here are given in the series of papers by Bruni and coworkers.^{14), 20)}

We have considered two gauge choices, represented by the groups of diffeomorphisms $\mathcal{X}_{\lambda,\epsilon}$ and $\mathcal{Y}_{\lambda,\epsilon}$, under which a point o on the physical spacetime $\mathcal{M}_{\lambda,\epsilon}$ corresponds to two different points in the background manifold \mathcal{M}_0 : $p = \mathcal{X}_{\lambda,\epsilon}^{-1}(o)$ and $q = \mathcal{Y}_{\lambda,\epsilon}^{-1}(o)$ as depicted in Fig. 1. The transformation relating these two gauge choices is described by the two-parameter family of diffeomorphisms $\Phi_{\lambda,\epsilon} = \mathcal{X}_{\lambda,\epsilon}^{-1} \circ \mathcal{Y}_{\lambda,\epsilon}$, so that $\Phi_{\lambda,\epsilon}(q) = p$. Under this gauge transformation, a tensor field Q on $p \in \mathcal{M}_0$ is pulled back to the tensor field $(\Phi^*Q)(q) = \Phi^*(Q(p))$ on $q \in \mathcal{M}_0$.

Now, let us consider a chart (\mathcal{U}, X) on an open subset \mathcal{U} of the background \mathcal{M}_0 . The coordinate system X is a map from the manifold \mathcal{M}_0 to \mathbb{R}^m . Since the gauges $\mathcal{X}_{\lambda,\epsilon}$ and $\mathcal{Y}_{\lambda,\epsilon}$ are maps from the background \mathcal{M}_0 to the physical spacetime $\mathcal{M}_{\lambda,\epsilon}$, these gauges define two maps from $\mathcal{M}_{\lambda,\epsilon}$ to \mathbb{R}^m :

$$\begin{aligned} X \circ \mathcal{X}_{\lambda,\epsilon}^{-1} : \mathcal{M}_{\lambda,\epsilon} &\rightarrow \mathbb{R}^m & X \circ \mathcal{Y}_{\lambda,\epsilon}^{-1} : \mathcal{M}_{\lambda,\epsilon} &\rightarrow \mathbb{R}^m \\ o &\mapsto x(p(o)), & o &\mapsto x(q(o)). \end{aligned} \quad (3.39)$$

The gauge transformation $\Phi_{\lambda,\epsilon}$ is regarded as the transformation of these maps.

It is well-known that there are two different points of view with which we can regard the gauge transformation $\Phi_{\lambda,\epsilon}$ as a change of the coordinate system, the *active* point of view and the *passive* point of view. In the *active* point of view, one considers a diffeomorphism that changes the point on the background \mathcal{M}_0 , and the coordinate change $x^\mu(p) \rightarrow \tilde{x}^\mu(p)$ is given according to the definition of the pull-back of x as

$$\tilde{x}^\mu(p) := x^\mu(\Phi(p)) \quad (3.40)$$

By contrast, in the *passive* point of view, we introduce a new chart (\mathcal{U}', Y) defined by $Y := X \circ \Phi_{\lambda,\epsilon}^{-1}$, and the two sets of coordinates are related by

$$y^\mu(p) = x^\mu(q). \quad (3.41)$$

In this *passive* point of view, the gauge transformation is regarded as not changing the point on \mathcal{M}_0 but changing the chart from (\mathcal{U}, X) to (\mathcal{U}', Y) (i.e. changing the labels of the points on \mathcal{M}_0). The coordinate transformation is given by $x^\mu(q) \rightarrow y^\mu(q)$.

Now, let us consider the transformation of a vector field V^a and the coordinate transformation from the *active* and *passive* points of view.

From the *active* point of view, the components V^μ of a vector field V^a in the chart (\mathcal{U}, X) are related to the components \tilde{V}^μ of the transformed vector field \tilde{V}^a as

$$\tilde{V}^\mu = (X_* \tilde{V})^* = (X_* \Phi_{\lambda, \epsilon}^* V)^\mu. \quad (3.42)$$

In order to write down explicit expressions, we apply the expansion of the pull-back of $\Phi_{\lambda, \epsilon}^*$ [see Eq. (2.14)] to the coordinate functions x^μ . Then, the *active* coordinate transformation is given by

$$\begin{aligned} \tilde{x}^\mu(p) &= x^\mu(q) = (\Phi^* x^\mu)(p) \\ &= x^\mu(p) + \lambda \xi_{(1,0)}^\mu + \epsilon \xi_{(0,1)}^\mu \\ &\quad + \frac{\lambda^2}{2} \left(\xi_{(2,0)}^\mu + \xi_{(1,0)}^\nu \partial_\nu \xi_{(1,0)}^\mu \right) + \frac{\epsilon^2}{2} \left(\xi_{(0,2)}^\mu + \xi_{(0,1)}^\nu \partial_\nu \xi_{(0,1)}^\mu \right) \\ &\quad + \lambda \epsilon \left(\xi_{(1,1)}^\mu + \frac{1}{2} \xi_{(1,0)}^\nu \partial_\nu \xi_{(0,1)}^\mu + \frac{1}{2} \xi_{(0,1)}^\nu \partial_\nu \xi_{(1,0)}^\mu \right) \\ &\quad + \frac{\lambda^3}{6} \left(\xi_{(3,0)}^\mu + 3 \xi_{(1,0)}^\nu \partial_\nu \xi_{(2,0)}^\mu + \xi_{(1,0)}^\rho \partial_\rho \xi_{(1,0)}^\nu \partial_\nu \xi_{(1,0)}^\mu \right) \\ &\quad + \frac{\lambda^2 \epsilon}{2} \left(\xi_{(2,1)}^\mu + 2 \xi_{(1,0)}^\nu \partial_\nu \xi_{(1,1)}^\mu + \xi_{(0,1)}^\nu \partial_\nu \xi_{(2,0)}^\mu \right. \\ &\quad \left. + \xi_{(1,0)}^\rho \partial_\rho \xi_{(0,1)}^\nu \partial_\nu \xi_{(1,0)}^\mu \right) \\ &\quad + \frac{\lambda \epsilon^2}{2} \left(\xi_{(1,2)}^\mu + 2 \xi_{(0,1)}^\nu \partial_\nu \xi_{(1,1)}^\mu + \xi_{(1,0)}^\nu \partial_\nu \xi_{(0,2)}^\mu \right. \\ &\quad \left. + \xi_{(0,1)}^\rho \partial_\rho \xi_{(1,0)}^\nu \partial_\nu \xi_{(0,1)}^\mu \right) \\ &\quad + \frac{\epsilon^3}{6} \left(\xi_{(0,3)}^\mu + 3 \xi_{(0,1)}^\nu \partial_\nu \xi_{(0,2)}^\mu + \xi_{(0,1)}^\rho \partial_\rho \xi_{(0,1)}^\nu \partial_\nu \xi_{(0,1)}^\mu \right) \\ &\quad + O^4(\lambda, \epsilon), \end{aligned} \quad (3.43)$$

where the vector fields $\xi_{(p,q)}^\mu$ and their derivatives are evaluated in $x(p)$. This expression gives the relation between the coordinates, in the chart (\mathcal{U}, X) , of the two different points p and q of \mathcal{M}_0 .

From the *passive* point of view, we can use the properties relating the pull-back and push-forward maps associated with diffeomorphisms,

$$X_* \Phi_{\lambda, \epsilon}^* V = X_* \Phi_{\lambda, \epsilon}^{-1} V = Y_* V. \quad (3.44)$$

Thus, we obtain the well-known result that the components of the transformed vector \tilde{V}^a in the coordinate system X are defined in terms of the components of the vector V^a in the new coordinate system Y :

$$\tilde{V}^\mu(x(p)) = (Y_* V(q))^\mu = V'^\mu(y(q)) = \left(\frac{\partial y^\mu}{\partial x^\nu} \right) \bigg|_{x(q)} V^\nu(x(q)). \quad (3.45)$$

In order to write down explicit expressions, we apply the expansion of the pull-back of $\Phi_{\lambda, \epsilon}^*$ [see Eq. (2.14)] to the coordinate functions x^μ . The *passive* coordinate

transformation is found by inverting (3.43). Using the representation (2.33) of the Taylor expansion of the inverse of $\Phi_{\lambda,\epsilon}^*$, we obtain the *passive* coordinate transformation:

$$\begin{aligned}
y^\mu(q) &:= x^\mu(p) = \left((\Phi^{-1})^* x^\mu \right) (q) \\
&= x^\mu(q) - \lambda \xi_{(1,0)}^\mu(q) - \epsilon \xi_{(0,1)}^\mu(q) \\
&\quad + \frac{\lambda^2}{2} \left\{ -\xi_{(2,0)}^\mu(q) + \xi_{(1,0)}^\nu(q) \partial_\nu \xi_{(1,0)}^\mu(q) \right\} \\
&\quad + \frac{\epsilon^2}{2} \left\{ -\xi_{(0,2)}^\mu(q) + \xi_{(0,1)}^\nu(q) \partial_\nu \xi_{(0,1)}^\mu(q) \right\} \\
&\quad + \lambda \epsilon \left\{ -\xi_{(1,1)}^\mu(q) + \frac{1}{2} \xi_{(1,0)}^\nu(q) \partial_\nu \xi_{(0,1)}^\mu(q) + \frac{1}{2} \xi_{(0,1)}^\nu(q) \partial_\nu \xi_{(1,0)}^\mu(q) \right\} \\
&\quad + \frac{\lambda^3}{6} \left\{ -\xi_{(3,0)}^\mu(q) + 3 \xi_{(2,0)}^\nu(q) \partial_\nu \xi_{(1,0)}^\mu(q) \right. \\
&\quad \quad \left. - \xi_{(1,0)}^\rho(q) \partial_\rho \left(\xi_{(1,0)}^\nu(q) \partial_\nu \xi_{(1,0)}^\mu(q) \right) \right\} \\
&\quad + \frac{\lambda^2 \epsilon}{2} \left\{ -\xi_{(2,1)}^\mu(q) + \xi_{(2,0)}^\nu(q) \partial_\nu \xi_{(0,1)}^\mu(q) + 2 \xi_{(1,1)}^\nu(q) \partial_\nu \xi_{(1,0)}^\mu(q) \right. \\
&\quad \quad \left. - \xi_{(1,0)}^\rho(q) \partial_\rho \left(\xi_{(0,1)}^\nu(q) \partial_\nu \xi_{(1,0)}^\mu(q) \right) \right\} \\
&\quad + \frac{\lambda \epsilon^2}{2} \left\{ -\xi_{(1,2)}^\mu(q) + \xi_{(0,2)}^\nu(q) \partial_\nu \xi_{(1,0)}^\mu(q) + 2 \xi_{(1,1)}^\nu(q) \partial_\nu \xi_{(0,1)}^\mu(q) \right. \\
&\quad \quad \left. - \xi_{(0,1)}^\rho(q) \partial_\rho \left(\xi_{(1,0)}^\nu(q) \partial_\nu \xi_{(0,1)}^\mu(q) \right) \right\} \\
&\quad + \frac{\epsilon^3}{6} \left\{ -\xi_{(0,3)}^\mu(q) + 3 \xi_{(0,2)}^\nu(q) \partial_\nu \xi_{(0,1)}^\mu(q) \right. \\
&\quad \quad \left. - \xi_{(0,1)}^\rho(q) \partial_\rho \left(\xi_{(0,1)}^\nu(q) \partial_\nu \xi_{(0,1)}^\mu(q) \right) \right\} \\
&\quad + O^4(\lambda, \epsilon). \tag{3.46}
\end{aligned}$$

This gives the relation between the coordinates of any arbitrary point $q \in \mathcal{M}_0$ in the two different charts (\mathcal{U}, X) and (\mathcal{U}', Y) .

§4. Gauge invariant variables of higher order perturbations

Now, we consider the definitions of gauge invariant variables for the perturbations. The gauge invariance we consider here is that up to order (n, n') for (n, n') -order perturbations as mentioned in §3.2. We do this because the gauge invariance to all orders is not so useful.^{(14), (15), (21)} Of course, the definition of gauge invariant variables is not unique, because any function of gauge invariant variables is also gauge invariant. In this section, we present one procedure to define gauge invariant variables. To do this, we first consider the procedure to obtain the gauge invariant variables for metric perturbations. Next, we extend the procedure to define gauge invariant variables for any physical variables, other than the metric.

4.1. Metric perturbations

As seen in Eqs. (3·14) and (3·15), we first consider the Taylor expansion of the spacetime metric $g_{ab}(\lambda, \epsilon)$ on $\mathcal{M}_{\lambda, \epsilon}$. As discuss in §3.2, the Taylor expansion of the spacetime metric up to third order is carried out by using a gauge choice \mathcal{X} on the background spacetime \mathcal{M}_0 :

$$\begin{aligned} \mathcal{X} g_{ab} &= {}^{(0)}g_{ab} + \sum_{k, k'=1}^{\infty} \frac{\lambda^k \epsilon^{k'}}{k! k'!} {}^{(k, k')}_{\mathcal{X}} h_{ab} \\ &= {}^{(0)}g_{ab} + \lambda {}^{(1,0)}_{\mathcal{X}} h_{ab} + \epsilon {}^{(0,1)}_{\mathcal{X}} h_{ab} + \frac{\lambda^2}{2} {}^{(2,0)}_{\mathcal{X}} h_{ab} + \lambda \epsilon {}^{(1,1)}_{\mathcal{X}} h_{ab} + \frac{\epsilon^2}{2} {}^{(0,2)}_{\mathcal{X}} h_{ab} \\ &\quad + \frac{\lambda^3}{3!} {}^{(3,0)}_{\mathcal{X}} h_{ab} + \frac{\lambda^2 \epsilon}{2} {}^{(2,1)}_{\mathcal{X}} h_{ab} + \frac{\lambda \epsilon^2}{2} {}^{(1,2)}_{\mathcal{X}} h_{ab} + \frac{\epsilon^3}{3!} {}^{(0,3)}_{\mathcal{X}} h_{ab} \\ &\quad + O(\lambda, \epsilon)^4. \end{aligned} \quad (4.1)$$

From Eqs. (3·30)–(3·38), the gauge transformation rules for the metric perturbations up to third order are given by

$${}^{(1,0)}_{\mathcal{Y}} h_{ab} - {}^{(1,0)}_{\mathcal{X}} h_{ab} = \mathcal{L}_{\xi_{(1,0)}} {}^{(0)}g_{ab}, \quad (4.2)$$

$${}^{(0,1)}_{\mathcal{Y}} h_{ab} - {}^{(0,1)}_{\mathcal{X}} h_{ab} = \mathcal{L}_{\xi_{(0,1)}} {}^{(0)}g_{ab}, \quad (4.3)$$

$${}^{(2,0)}_{\mathcal{Y}} h_{ab} - {}^{(2,0)}_{\mathcal{X}} h_{ab} = 2\mathcal{L}_{\xi_{(1,0)}} {}^{(1,0)}_{\mathcal{X}} h_{ab} + \left\{ \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}}^2 \right\} {}^{(0)}g_{ab}, \quad (4.4)$$

$$\begin{aligned} {}^{(1,1)}_{\mathcal{Y}} h_{ab} - {}^{(1,1)}_{\mathcal{X}} h_{ab} &= \mathcal{L}_{\xi_{(1,0)}} {}^{(0,1)}_{\mathcal{X}} h_{ab} + \mathcal{L}_{\xi_{(0,1)}} {}^{(1,0)}_{\mathcal{X}} h_{ab} \\ &\quad + \left\{ \mathcal{L}_{\xi_{(1,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right\} {}^{(0)}g_{ab}, \end{aligned} \quad (4.5)$$

$${}^{(0,2)}_{\mathcal{Y}} h_{ab} - {}^{(0,2)}_{\mathcal{X}} h_{ab} = 2\mathcal{L}_{\xi_{(0,1)}} {}^{(0,1)}_{\mathcal{X}} h_{ab} + \left\{ \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}}^2 \right\} {}^{(0)}g_{ab}, \quad (4.6)$$

$$\begin{aligned} {}^{(3,0)}_{\mathcal{Y}} h_{ab} - {}^{(3,0)}_{\mathcal{X}} h_{ab} &= 3\mathcal{L}_{\xi_{(1,0)}} {}^{(2,0)}_{\mathcal{X}} h_{ab} + 3 \left\{ \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}}^2 \right\} {}^{(1,0)}_{\mathcal{X}} h_{ab} \\ &\quad + \left\{ \mathcal{L}_{\xi_{(3,0)}} + 3\mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}}^3 \right\} {}^{(0)}g_{ab}, \end{aligned} \quad (4.7)$$

$$\begin{aligned} {}^{(2,1)}_{\mathcal{Y}} h_{ab} - {}^{(2,1)}_{\mathcal{X}} h_{ab} &= 2\mathcal{L}_{\xi_{(1,0)}} {}^{(1,1)}_{\mathcal{X}} h_{ab} + \mathcal{L}_{\xi_{(0,1)}} {}^{(2,0)}_{\mathcal{X}} h_{ab} \\ &\quad + \left\{ \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}}^2 \right\} {}^{(0,1)}_{\mathcal{X}} h_{ab} \\ &\quad + 2 \left\{ \mathcal{L}_{\xi_{(1,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right\} {}^{(1,0)}_{\mathcal{X}} h_{ab} \\ &\quad + \left\{ \mathcal{L}_{\xi_{(2,1)}} + 2\mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(1,1)}} + \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(2,0)}} \right. \\ &\quad \left. + \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right\} {}^{(0)}g_{ab}, \end{aligned} \quad (4.8)$$

$$\begin{aligned} {}^{(1,2)}_{\mathcal{Y}} h_{ab} - {}^{(1,2)}_{\mathcal{X}} h_{ab} &= 2\mathcal{L}_{\xi_{(0,1)}} {}^{(1,1)}_{\mathcal{X}} h_{ab} + \mathcal{L}_{\xi_{(1,0)}} {}^{(0,2)}_{\mathcal{X}} h_{ab} \\ &\quad + \left\{ \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}}^2 \right\} {}^{(1,0)}_{\mathcal{X}} h_{ab} \\ &\quad + 2 \left\{ \mathcal{L}_{\xi_{(1,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right\} {}^{(0,1)}_{\mathcal{X}} h_{ab} \end{aligned}$$

$$+ \left\{ \mathcal{L}_{\xi(1,2)} + 2\mathcal{L}_{\xi(0,1)}\mathcal{L}_{\xi(1,1)} + \mathcal{L}_{\xi(1,0)}\mathcal{L}_{\xi(0,2)} + \mathcal{L}_{\xi(0,1)}\mathcal{L}_{\xi(1,0)}\mathcal{L}_{\xi(0,1)} \right\}^{(0)}g_{ab}, \quad (4.9)$$

$$\begin{aligned} {}^{(0,3)}_{\mathcal{Y}}h_{ab} - {}^{(0,3)}_{\mathcal{X}}h_{ab} &= 3\mathcal{L}_{\xi(0,1)}{}^{(0,2)}_{\mathcal{X}}h_{ab} + 3\left\{ \mathcal{L}_{\xi(0,2)} + \mathcal{L}_{\xi(0,1)}^2 \right\}{}^{(0,1)}_{\mathcal{X}}h_{ab} \\ &+ \left\{ \mathcal{L}_{\xi(0,3)} + 3\mathcal{L}_{\xi(0,1)}\mathcal{L}_{\xi(0,2)} + \mathcal{L}_{\xi(0,1)}^3 \right\}{}^{(0)}g_{ab}. \end{aligned} \quad (4.10)$$

Inspecting these transformation rules, we consider the procedure to separate the gauge invariant parts and gauge variant parts of the metric perturbation at each order. The aim of this paper is to show that this separation for higher order perturbations can be carried out with the same procedure as for linear perturbation theory. In other words, if we are able to carry out this separation at linear order, the separation for higher order perturbations can also be carried out.

4.1.1. Linear order perturbations

Suppose that, inspecting the gauge transformation rules (4.2) and (4.3), the $O(\lambda)$ and $O(\epsilon)$ perturbations can be decomposed as

$$\begin{aligned} {}^{(1,0)}_{\mathcal{X}}h_{ab} &=: {}^{(1,0)}_{\mathcal{X}}\mathcal{H}_{ab} + \nabla_a {}^{(1,0)}_{\mathcal{X}}X_b + \nabla_b {}^{(1,0)}_{\mathcal{X}}X_a, \\ {}^{(0,1)}_{\mathcal{X}}h_{ab} &=: {}^{(0,1)}_{\mathcal{X}}\mathcal{H}_{ab} + \nabla_a {}^{(0,1)}_{\mathcal{X}}X_b + \nabla_b {}^{(0,1)}_{\mathcal{X}}X_a, \end{aligned} \quad (4.11)$$

so that the variables ${}^{(1,0)}_{\mathcal{X}}\mathcal{H}_{ab}$ and ${}^{(0,1)}_{\mathcal{X}}\mathcal{H}_{ab}$ are gauge invariant; i.e.,

$${}^{(1,0)}_{\mathcal{Y}}\mathcal{H}_{ab} - {}^{(1,0)}_{\mathcal{X}}\mathcal{H}_{ab} = 0, \quad {}^{(0,1)}_{\mathcal{Y}}\mathcal{H}_{ab} - {}^{(0,1)}_{\mathcal{X}}\mathcal{H}_{ab} = 0, \quad (4.12)$$

under the gauge transformation $\Phi = \mathcal{X}^{-1} \circ \mathcal{Y}$. Next, note that the vector fields ${}^{(1,0)}_{\mathcal{X}}X_a$ and ${}^{(0,1)}_{\mathcal{X}}X_a$ are transformed as

$${}^{(1,0)}_{\mathcal{Y}}X^a - {}^{(1,0)}_{\mathcal{X}}X^a = \xi_{(1,0)}^a, \quad {}^{(0,1)}_{\mathcal{Y}}X^a - {}^{(0,1)}_{\mathcal{X}}X^a = \xi_{(0,1)}^a; \quad (4.13)$$

i.e., ${}^{(1,0)}_{\mathcal{X}}X^a$ and ${}^{(0,1)}_{\mathcal{X}}X^a$ are the gauge variant parts of the metric perturbations ${}^{(1,0)}_{\mathcal{X}}h_{ab}$ and ${}^{(0,1)}_{\mathcal{X}}h_{ab}$, respectively. We also note that the number of independent components of ${}^{(1,0)}_{\mathcal{X}}\mathcal{H}_{ab}$ (or ${}^{(0,1)}_{\mathcal{X}}\mathcal{H}_{ab}$) is $m(m-1)/2$, where m is the dimension of the spacetime manifold.

It is non-trivial to carry out the systematic decomposition (4.11) on an arbitrary background spacetime, and the procedure completely depends on the background spacetime $(\mathcal{M}_0, {}^{(0)}g_{ab})$. For simple background spacetimes in which there are some Killing symmetries, one useful type of analyses to carry out the decomposition (4.11) is that based on the expansion in harmonic functions on a submanifold of the background spacetime $(\mathcal{M}_0, {}^{(0)}g_{ab})$.^{3),22),5)} For example, the harmonic functions on a homogeneous and isotropic three-dimensional space are used in cosmological perturbation theory.³⁾ Analyses based on a harmonic expansion depend strongly on not only local symmetries of the background spacetime but also the global topology of the submanifold on which scalar, vector, and tensor harmonics are defined.

In spite of the non-trivial nature of this decomposition, we assume that the decomposition (4.11) can always be carried out in some manner. What is necessary for our discussion here is only the result of the extraction of m gauge variant components from $m(m+1)/2$ components of the metric perturbations $^{(1,0)}_{\mathcal{X}}h_{ab}$ or $^{(0,1)}_{\mathcal{X}}h_{ab}$. The details to realize the decomposition (4.11) are not important to our discussion, though the existence of the procedure is crucial. As seen below, if such a procedure exists, we can easily show that the procedure to define the gauge invariant variables of higher order metric perturbations is reduced to that for linear perturbations, whose existence we assume. Though a generic formula to define gauge invariant variables for any order perturbation might exist, we give only the formulae for two-parameter perturbations up to third order.

4.1.2. Second order perturbations

Here, we consider the definitions of gauge invariant variables for $O(\lambda^2)$, $O(\epsilon^2)$ and $O(\lambda\epsilon)$ metric perturbations.

First, we consider the $O(\lambda^2)$ metric perturbation. The metric perturbation $^{(2,0)}h_{ab}$ of this order is transformed as in Eq. (4.4) under the gauge transformation $\Phi = \mathcal{X}^{-1} \circ \mathcal{Y}$. Inspecting this transformation rule, we define a variable $^{(2,0)}_{\mathcal{X}}\hat{\mathcal{H}}_{ab}$ with the gauge \mathcal{X} by

$$^{(2,0)}_{\mathcal{X}}\hat{\mathcal{H}}_{ab} := ^{(2,0)}_{\mathcal{X}}h_{ab} - 2\mathcal{L}_{^{(1,0)}_{\mathcal{X}}X}^{(1,0)}_{\mathcal{X}}h_{ab} + \mathcal{L}_{^{(1,0)}_{\mathcal{X}}X}^2{}^{(0)}g_{ab}. \quad (4.14)$$

We also define a variable $^{(2,0)}_{\mathcal{Y}}\hat{\mathcal{H}}_{ab}$ with the gauge \mathcal{Y} by simply replacing \mathcal{X} with \mathcal{Y} in Eq. (4.14). Using the gauge transformation rules (4.2), (4.4), and (4.13), we can easily check that the variable $^{(2,0)}_{\mathcal{Y}}\hat{\mathcal{H}}_{ab}$ is transformed as

$$^{(2,0)}_{\mathcal{Y}}\hat{\mathcal{H}}_{ab} - ^{(2,0)}_{\mathcal{X}}\hat{\mathcal{H}}_{ab} = \mathcal{L}_{\sigma_{(2,0)}}^{(0)}g_{ab}, \quad (4.15)$$

where the vector field $\sigma_{(2,0)}^a$ is defined by

$$\sigma_{(2,0)}^a := \xi_{(2,0)}^a + [\xi_{(1,0)}, ^{(1,0)}_{\mathcal{X}}X]^a. \quad (4.16)$$

We note that the gauge transformation rule (4.15) has the same form as the gauge transformation rules (4.2) and (4.3) of the linear metric perturbations. Because we assume that the procedure to decompose a tensor field of second rank, which transforms as (4.2) or (4.3), into the form (4.11) exists, the transformation rule (4.15) implies that we can decompose the tensor $^{(2,0)}_{\mathcal{X}}\hat{\mathcal{H}}_{ab}$ into a tensor field $^{(2,0)}_{\mathcal{X}}\mathcal{H}_{ab}$ and a vector field $^{(2,0)}_{\mathcal{X}}X^b$ as

$$^{(2,0)}_{\mathcal{X}}\hat{\mathcal{H}}_{ab} =: ^{(2,0)}_{\mathcal{X}}\mathcal{H}_{ab} + \nabla_a ^{(2,0)}_{\mathcal{X}}X_b + \nabla_b ^{(2,0)}_{\mathcal{X}}X_a, \quad (4.17)$$

where the tensor $^{(2,0)}_{\mathcal{X}}\mathcal{H}_{ab}$ is gauge invariant, i.e.,

$$^{(2,0)}_{\mathcal{Y}}\mathcal{H}_{ab} - ^{(2,0)}_{\mathcal{X}}\mathcal{H}_{ab} = 0, \quad (4.18)$$

and the vector ${}^{(2,0)}_{\mathcal{X}}X_a$ is gauge variant, i.e.,

$${}^{(2,0)}_{\mathcal{Y}}X^a - {}^{(2,0)}_{\mathcal{X}}X^a = \xi^a_{(2,0)} + [\xi_{(1,0)}, {}^{(1,0)}_{\mathcal{X}}X]^a. \quad (4.19)$$

Thus, we can extract the gauge invariant part ${}^{(2,0)}\mathcal{H}_{ab}$ of the $O(\lambda^2)$ metric perturbation using the procedure to define the gauge invariant variables for linear order metric perturbations.

The extraction of the gauge invariant part from the $O(\epsilon^2)$ metric perturbation is accomplished in a manner that is completely parallel to the above procedure for $O(\lambda^2)$ perturbations. First, we define the variable ${}^{(0,2)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab}$ by

$${}^{(0,2)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab} := {}^{(0,2)}_{\mathcal{X}}h_{ab} - 2\mathcal{L}_{(0,1)_{\mathcal{X}}X}{}^{(0,1)}_{\mathcal{X}}h_{ab} + \mathcal{L}_{(0,1)_{\mathcal{X}}X}^2{}^{(0)}g_{ab}, \quad (4.20)$$

with the gauge \mathcal{X} . From the gauge transformation rules (4.3), (4.6) and (4.13), the variable ${}^{(0,2)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab}$ is transformed as

$${}^{(0,2)}_{\mathcal{Y}}\widehat{\mathcal{H}}_{ab} - {}^{(0,2)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab} = \mathcal{L}_{\sigma_{(0,2)}}{}^{(0)}g_{ab}, \quad (4.21)$$

under the gauge transformation $\mathcal{X} \rightarrow \mathcal{Y}$, where

$$\sigma^a_{(0,2)} := \xi^a_{(0,2)} + [\xi_{(0,1)}, {}^{(0,1)}_{\mathcal{X}}X]^a. \quad (4.22)$$

Because the gauge transformation rule (4.21) has the same form as that for the linear-order metric perturbations, (4.2) and (4.3), we can decompose the variable ${}^{(0,2)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab}$ as

$${}^{(0,2)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab} =: {}^{(0,2)}_{\mathcal{X}}\mathcal{H}_{ab} + \nabla_a{}^{(0,2)}_{\mathcal{X}}X_b + \nabla_b{}^{(0,2)}_{\mathcal{X}}X_a, \quad (4.23)$$

where ${}^{(0,2)}_{\mathcal{X}}\mathcal{H}_{ab}$ is gauge invariant, and the vector field ${}^{(0,2)}_{\mathcal{X}}X_a$ is the gauge variant part of the $O(\epsilon^2)$ metric perturbations. The vector field ${}^{(0,2)}_{\mathcal{X}}X_a$ is transformed as

$${}^{(0,2)}_{\mathcal{Y}}X^a - {}^{(0,2)}_{\mathcal{X}}X^a = \xi^a_{(0,2)} + [\xi_{(0,1)}, {}^{(0,1)}_{\mathcal{X}}X]^a \quad (4.24)$$

under the gauge transformation $\mathcal{X} \rightarrow \mathcal{Y}$. Thus, we can find the gauge invariant part ${}^{(0,2)}\mathcal{H}_{ab}$ of the $O(\epsilon^2)$ metric perturbation.

In a similar way, we can also define the gauge invariant variables of the $O(\epsilon\lambda)$ metric perturbation ${}^{(1,1)}_{\mathcal{X}}h_{ab}$. The $O(\epsilon\lambda)$ metric perturbation is transformed as in Eq. (4.5) under the gauge transformation $\mathcal{X} \rightarrow \mathcal{Y}$. Inspecting this gauge transformation rule, we first define the variable ${}^{(1,1)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab}$ by

$$\begin{aligned} {}^{(1,1)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab} := & {}^{(1,1)}_{\mathcal{X}}h_{ab} - \mathcal{L}_{(0,1)_{\mathcal{X}}X}{}^{(1,0)}_{\mathcal{X}}h_{ab} - \mathcal{L}_{(1,0)_{\mathcal{X}}X}{}^{(0,1)}_{\mathcal{X}}h_{ab} \\ & + \frac{1}{2} \left\{ \mathcal{L}_{(1,0)_{\mathcal{X}}X} \mathcal{L}_{(0,1)_{\mathcal{X}}X} + \mathcal{L}_{(0,1)_{\mathcal{X}}X} \mathcal{L}_{(1,0)_{\mathcal{X}}X} \right\} {}^{(0)}g_{ab} \end{aligned} \quad (4.25)$$

in the gauge \mathcal{X} . The variable ${}^{(1,1)}_{\mathcal{Y}}\widehat{\mathcal{H}}_{ab}$ is defined in the gauge \mathcal{Y} in the same form as Eq. (4.25), with the replacement $\mathcal{X} \rightarrow \mathcal{Y}$. Using the gauge transformation rules (4.2),

(4.3), (4.5) and (4.13), we can easily check that the variable ${}^{(1,1)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab}$ is transformed as

$${}^{(1,1)}_{\mathcal{Y}}\widehat{\mathcal{H}}_{ab} - {}^{(1,1)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab} = \mathcal{L}_{\sigma_{(1,1)}}^{(0)} g_{ab}, \quad (4.26)$$

where the vector field $\sigma_{(1,1)}$ is defined by

$$\sigma_{(1,1)}^a = \xi_{(1,1)}^a + \frac{1}{2}[\xi_{(0,1)}, {}^{(1,0)}_{\mathcal{X}}X]^a + \frac{1}{2}[\xi_{(1,0)}, {}^{(0,1)}_{\mathcal{X}}X]^a. \quad (4.27)$$

Here again, we have the gauge transformation rule (4.26), which has the same form as that for linear perturbations given in (4.2) and (4.3). Then, as in the previous cases of (2, 0) and (0, 2) order perturbations, we can decompose the variables ${}^{(1,1)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab}$ as

$${}^{(1,1)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab} =: {}^{(1,1)}_{\mathcal{X}}\mathcal{H}_{ab} + \nabla_a {}^{(1,1)}_{\mathcal{X}}X_b + \nabla_b {}^{(1,1)}_{\mathcal{X}}X_a, \quad (4.28)$$

where ${}^{(1,1)}_{\mathcal{X}}\mathcal{H}_{ab}$ is gauge invariant and ${}^{(1,1)}_{\mathcal{X}}X_a$ transforms as

$${}^{(1,1)}_{\mathcal{Y}}X^a = {}^{(1,1)}_{\mathcal{X}}X^a + \xi_{(1,1)}^a + \frac{1}{2}[\xi_{(0,1)}, {}^{(1,0)}_{\mathcal{X}}X]^a + \frac{1}{2}[\xi_{(1,0)}, {}^{(0,1)}_{\mathcal{X}}X]^a. \quad (4.29)$$

4.1.3. Third order metric perturbation

Finally, we give the definitions of the gauge invariant variables for third order metric perturbations. The procedure to define gauge invariant variables is completely parallel to that in the case of second order perturbations. First, we define the variables ${}^{(p,q)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab}$ at each order in such a way that their gauge transformation rules have the same form as those for the linear perturbations. If we define the variable ${}^{(p,q)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab}$, we can extract the gauge invariant part of the higher order perturbation theory from this variable using the procedure employed for the linear perturbations of the metric.

The non-trivial point of this procedure lies only in defining the variables ${}^{(p,q)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab}$. The remaining part is trivial, due to the assumption that there exists a procedure for the linear perturbation theory. The definitions of the variables ${}^{(p,q)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab}$ of $O(\lambda^3)$, $O(\lambda^2\epsilon)$, $O(\lambda\epsilon^2)$ and $O(\epsilon^3)$ are as follows:

$$\begin{aligned} {}^{(3,0)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab} &:= {}^{(3,0)}_{\mathcal{X}}h_{ab} - 3\mathcal{L}_{(1,0)_{\mathcal{X}}X}{}^{(2,0)}_{\mathcal{X}}h_{ab} - 3\mathcal{L}_{(2,0)_{\mathcal{X}}X}{}^{(1,0)}_{\mathcal{X}}h_{ab} + 3\mathcal{L}_{(1,0)_{\mathcal{X}}X}^2{}^{(1,0)}_{\mathcal{X}}h_{ab} \\ &\quad + \left\{ 3\mathcal{L}_{(1,0)_{\mathcal{X}}X}\mathcal{L}_{(2,0)_{\mathcal{X}}X} - \mathcal{L}_{(1,0)_{\mathcal{X}}X}^3 \right\} {}^{(0)}g_{ab}, \\ {}^{(2,1)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab} &:= {}^{(2,1)}_{\mathcal{X}}h_{ab} - 2\mathcal{L}_{(1,0)_{\mathcal{X}}X}{}^{(1,1)}_{\mathcal{X}}h_{ab} - \mathcal{L}_{(0,1)_{\mathcal{X}}X}{}^{(2,0)}_{\mathcal{X}}h_{ab} \\ &\quad - \left(\mathcal{L}_{(2,0)_{\mathcal{X}}X} - \mathcal{L}_{(1,0)_{\mathcal{X}}X}^2 \right) {}^{(0,1)}_{\mathcal{X}}h_{ab} \\ &\quad - 2 \left\{ \mathcal{L}_{(1,1)_{\mathcal{X}}X} - \frac{1}{2} \left(\mathcal{L}_{(1,0)_{\mathcal{X}}X}\mathcal{L}_{(0,1)_{\mathcal{X}}X} + \mathcal{L}_{(0,1)_{\mathcal{X}}X}\mathcal{L}_{(1,0)_{\mathcal{X}}X} \right) \right\} {}^{(1,0)}_{\mathcal{X}}h_{ab} \\ &\quad + \left(2\mathcal{L}_{(1,0)_{\mathcal{X}}X}\mathcal{L}_{(1,1)_{\mathcal{X}}X} + \mathcal{L}_{(0,1)_{\mathcal{X}}X}\mathcal{L}_{(2,0)_{\mathcal{X}}X} \right) \end{aligned} \quad (4.30)$$

$$- \mathcal{L}_{(1,0)}^{(0)} X \mathcal{L}_{(0,1)}^{(0)} X \mathcal{L}_{(1,0)}^{(0)} X \Big)^{(0)} g_{ab}, \quad (4.31)$$

$$\begin{aligned} {}^{(1,2)}_{\mathcal{X}} \widehat{\mathcal{H}}_{ab} := & {}^{(1,2)}_{\mathcal{X}} h_{ab} - 2 \mathcal{L}_{(0,1)}^{(1,1)} X \mathcal{L}_{(1,0)}^{(1,1)} X h_{ab} - \mathcal{L}_{(1,0)}^{(0,2)} X \mathcal{L}_{(0,1)}^{(0,2)} X h_{ab} \\ & - \left(\mathcal{L}_{(0,2)}^{(1,0)} X - \mathcal{L}_{(0,1)}^{(2,0)} X \right) {}^{(1,0)}_{\mathcal{X}} h_{ab} \\ & - 2 \left\{ \mathcal{L}_{(1,1)}^{(1,1)} X - \frac{1}{2} \left(\mathcal{L}_{(1,0)}^{(1,0)} X \mathcal{L}_{(0,1)}^{(1,0)} X + \mathcal{L}_{(0,1)}^{(0,1)} X \mathcal{L}_{(1,0)}^{(1,0)} X \right) \right\} {}^{(0,1)}_{\mathcal{X}} h_{ab} \\ & + \left(2 \mathcal{L}_{(0,1)}^{(0,1)} X \mathcal{L}_{(1,1)}^{(1,1)} X + \mathcal{L}_{(1,0)}^{(1,0)} X \mathcal{L}_{(0,2)}^{(0,2)} X \right. \\ & \quad \left. - \mathcal{L}_{(0,1)}^{(0,1)} X \mathcal{L}_{(1,0)}^{(1,0)} X \mathcal{L}_{(0,1)}^{(0,1)} X \right) {}^{(0)}_{\mathcal{X}} g_{ab}, \end{aligned} \quad (4.32)$$

$$\begin{aligned} {}^{(0,3)}_{\mathcal{X}} \widehat{\mathcal{H}}_{ab} := & {}^{(0,3)}_{\mathcal{X}} h_{ab} - 3 \mathcal{L}_{(0,1)}^{(0,2)} X \mathcal{L}_{(0,1)}^{(0,2)} X h_{ab} - 3 \mathcal{L}_{(0,2)}^{(0,1)} X \mathcal{L}_{(0,1)}^{(0,1)} X h_{ab} + 3 \mathcal{L}_{(0,1)}^{(2,0)} X \mathcal{L}_{(0,1)}^{(0,1)} X h_{ab} \\ & + \left\{ 3 \mathcal{L}_{(0,1)}^{(0,1)} X \mathcal{L}_{(0,2)}^{(0,2)} X - \mathcal{L}_{(0,1)}^{(3,0)} X \right\} {}^{(0)}_{\mathcal{X}} g_{ab} \end{aligned} \quad (4.33)$$

with the gauge \mathcal{X} . The variables ${}^{(p,q)}_{\mathcal{Y}} \widehat{\mathcal{H}}_{ab}$ for $p+q=3$ are defined for the gauge \mathcal{Y} in same forms as Eqs. (4.30)–(4.33) with the replacement $\mathcal{X} \rightarrow \mathcal{Y}$. Using the gauge transformation rules (4.2)–(4.10), (4.13), (4.24) and (4.29), we can easily check that the variable ${}^{(p,q)}_{\mathcal{X}} \widehat{\mathcal{H}}_{ab}$ ($p+q=3$) is transformed as

$${}^{(p,q)}_{\mathcal{Y}} \widehat{\mathcal{H}}_{ab} - {}^{(p,q)}_{\mathcal{X}} \widehat{\mathcal{H}}_{ab} = \mathcal{L}_{\sigma_{(p,q)}} {}^{(0)}_{\mathcal{X}} g_{ab}, \quad (4.34)$$

where the vector fields $\sigma_{(p,q)}^a$ are defined by

$$\begin{aligned} \sigma_{(3,0)}^a := & \xi_{(3,0)}^a - 3 \left[\xi_{(2,0)} + {}^{(2,0)}_{\mathcal{X}} X, \xi_{(1,0)} \right]^a \\ & + \left[2 \xi_{(1,0)} + {}^{(1,0)}_{\mathcal{X}} X, \left[\xi_{(1,0)}, {}^{(1,0)}_{\mathcal{X}} X \right] \right]^a, \end{aligned} \quad (4.35)$$

$$\begin{aligned} \sigma_{(2,1)}^a := & \xi_{(2,1)}^a + \left[\left[{}^{(0,1)}_{\mathcal{X}} X, \xi_{(1,0)} \right] - 2 {}^{(1,1)}_{\mathcal{X}} X - 2 \xi_{(1,1)}, \xi_{(1,0)} \right]^a \\ & + \left[\left[{}^{(1,0)}_{\mathcal{X}} X, \xi_{(1,0)} \right] - {}^{(2,0)}_{\mathcal{X}} X - \xi_{(2,0)}, \xi_{(0,1)} \right]^a \\ & + \left[{}^{(1,0)}_{\mathcal{X}} X, \left[\xi_{(1,0)}, {}^{(0,1)}_{\mathcal{X}} X \right] \right]^a, \end{aligned} \quad (4.36)$$

$$\begin{aligned} \sigma_{(1,2)}^a := & \xi_{(1,2)}^a + \left[\left[{}^{(1,0)}_{\mathcal{X}} X, \xi_{(0,1)} \right] - 2 {}^{(1,1)}_{\mathcal{X}} X - 2 \xi_{(1,1)}, \xi_{(0,1)} \right]^a \\ & + \left[\left[{}^{(0,1)}_{\mathcal{X}} X, \xi_{(1,0)} \right] - {}^{(0,2)}_{\mathcal{X}} X - \xi_{(0,2)}, \xi_{(1,0)} \right]^a \\ & + \left[{}^{(0,1)}_{\mathcal{X}} X, \left[\xi_{(0,1)}, {}^{(1,0)}_{\mathcal{X}} X \right] \right]^a, \end{aligned} \quad (4.37)$$

$$\begin{aligned} \sigma_{(0,3)}^a := & \xi_{(0,3)}^a - 3 \left[\xi_{(0,2)} + {}^{(0,2)}_{\mathcal{X}} X, \xi_{(0,1)} \right]^a \\ & + \left[2 \xi_{(0,1)} + {}^{(0,1)}_{\mathcal{X}} X, \left[\xi_{(0,1)}, {}^{(0,1)}_{\mathcal{X}} X \right] \right]^a. \end{aligned} \quad (4.38)$$

The gauge transformations given in (4.34) imply that we can decompose the

variables ${}^{(p,q)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab}$ as

$${}^{(p,q)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab} := {}^{(p,q)}_{\mathcal{X}}\mathcal{H}_{ab} + \nabla_a {}^{(p,q)}_{\mathcal{X}}X_b + \nabla_b {}^{(p,q)}_{\mathcal{X}}X_a, \quad (4.39)$$

using the procedure to find the gauge invariant variables for linear order perturbations, where ${}^{(p,q)}_{\mathcal{X}}\mathcal{H}_{ab}$ is gauge invariant and ${}^{(p,q)}_{\mathcal{X}}X_a$ at each order is transformed as

$$\begin{aligned} {}^{(3,0)}_{\mathcal{Y}}X^a - {}^{(3,0)}_{\mathcal{X}}X^a &= \xi_{(3,0)}^a - 3 \left[\xi_{(2,0)} + {}^{(2,0)}_{\mathcal{X}}X, \xi_{(1,0)} \right]^a \\ &\quad + \left[2\xi_{(1,0)} + {}^{(1,0)}_{\mathcal{X}}X, \left[\xi_{(1,0)}, {}^{(1,0)}_{\mathcal{X}}X \right] \right]^a, \end{aligned} \quad (4.40)$$

$$\begin{aligned} {}^{(2,1)}_{\mathcal{Y}}X^a - {}^{(2,1)}_{\mathcal{X}}X^a &= \xi_{(2,1)}^a + \left[\left[{}^{(0,1)}_{\mathcal{X}}X, \xi_{(1,0)} \right] - 2{}^{(1,1)}_{\mathcal{X}}X - 2\xi_{(1,1)}, \xi_{(1,0)} \right]^a \\ &\quad + \left[\left[{}^{(1,0)}_{\mathcal{X}}X, \xi_{(1,0)} \right] - {}^{(1,1)}_{\mathcal{X}}X - \xi_{(1,1)}, \xi_{(0,1)} \right]^a \\ &\quad + \left[{}^{(1,0)}_{\mathcal{X}}X, \left[\xi_{(1,0)}, {}^{(0,1)}_{\mathcal{X}}X \right] \right]^a, \end{aligned} \quad (4.41)$$

$$\begin{aligned} {}^{(1,2)}_{\mathcal{Y}}X^a - {}^{(1,2)}_{\mathcal{X}}X^a &= \xi_{(1,2)}^a + \left[\left[{}^{(1,0)}_{\mathcal{X}}X, \xi_{(0,1)} \right] - 2{}^{(1,1)}_{\mathcal{X}}X - 2\xi_{(1,1)}, \xi_{(0,1)} \right]^a \\ &\quad + \left[\left[{}^{(0,1)}_{\mathcal{X}}X, \xi_{(1,0)} \right] - {}^{(0,2)}_{\mathcal{X}}X - \xi_{(0,2)}, \xi_{(1,0)} \right]^a \\ &\quad + \left[{}^{(0,1)}_{\mathcal{X}}X, \left[\xi_{(0,1)}, {}^{(1,0)}_{\mathcal{X}}X \right] \right]^a, \end{aligned} \quad (4.42)$$

$$\begin{aligned} {}^{(0,3)}_{\mathcal{Y}}X^a - {}^{(0,3)}_{\mathcal{X}}X^a &= \xi_{(0,3)}^a - 3 \left[\xi_{(0,2)} + {}^{(0,2)}_{\mathcal{X}}X, \xi_{(0,1)} \right]^a \\ &\quad + 2 \left[2\xi_{(0,1)} + {}^{(0,1)}_{\mathcal{X}}X, \left[\xi_{(0,1)}, {}^{(0,1)}_{\mathcal{X}}X \right] \right]^a. \end{aligned} \quad (4.43)$$

Thus, we have found recursively the gauge invariant variables for higher order metric perturbations up to third order.

4.2. Gauge invariant variables for matter perturbations

As shown above, we can find the gauge invariant variables of higher order metric perturbations. To do so, we have decomposed the metric perturbations at each order into the gauge invariant variables ${}^{(p,q)}_{\mathcal{X}}\mathcal{H}_{ab}$ and the gauge variant vector variables ${}^{(p,q)}_{\mathcal{X}}X_a$. The gauge variant parts, ${}^{(p,q)}_{\mathcal{X}}X_a$ of the $O(\lambda^p\epsilon^q)$ metric perturbations are irrelevant as physical metric perturbations. However, using these gauge variant parts, we can define the gauge invariant variables for the physical fields, other than the metric.

Here, we give explicit definitions of gauge invariant variables for perturbations of an arbitrary tensor field Q up to third order:

$$\delta_{\mathcal{X}}^{(1,0)}\mathcal{Q} := \delta_{\mathcal{X}}^{(1,0)}Q - \mathcal{L}_{(1,0)\mathcal{X}}X Q_0, \quad (4.44)$$

$$\delta_{\mathcal{X}}^{(0,1)}\mathcal{Q} := \delta_{\mathcal{X}}^{(0,1)}Q - \mathcal{L}_{(0,1)\mathcal{X}}X Q_0, \quad (4.45)$$

$$\delta_{\mathcal{X}}^{(2,0)}\mathcal{Q} := \delta_{\mathcal{X}}^{(2,0)}Q - 2\mathcal{L}_{(1,0)\mathcal{X}}X \delta_{\mathcal{X}}^{(1,0)}Q - \left\{ \mathcal{L}_{(2,0)\mathcal{X}}X - \mathcal{L}_{(1,0)\mathcal{X}}^2X \right\} Q_0, \quad (4.46)$$

$$\begin{aligned} \delta_{\mathcal{X}}^{(1,1)} \mathcal{Q} := & \delta_{\mathcal{X}}^{(1,1)} Q - \mathcal{L}_{(1,0)\mathcal{X}X} \delta_{\mathcal{X}}^{(0,1)} Q - \mathcal{L}_{(0,1)\mathcal{X}X} \delta_{\mathcal{X}}^{(1,0)} Q \\ & - \left\{ \mathcal{L}_{(1,1)\mathcal{X}X} - \frac{1}{2} \mathcal{L}_{(1,0)\mathcal{X}X} \mathcal{L}_{(0,1)\mathcal{X}X} - \frac{1}{2} \mathcal{L}_{(0,1)\mathcal{X}X} \mathcal{L}_{(1,0)\mathcal{X}X} \right\} Q_0, \end{aligned} \quad (4.47)$$

$$\delta_{\mathcal{X}}^{(0,2)} \mathcal{Q} = \delta_{\mathcal{X}}^{(0,2)} Q - 2 \mathcal{L}_{(0,1)\mathcal{X}X} \delta_{\mathcal{X}}^{(0,1)} Q - \left\{ \mathcal{L}_{(0,2)\mathcal{X}X} - \mathcal{L}_{(0,2)\mathcal{X}X}^2 \right\} Q_0, \quad (4.48)$$

$$\begin{aligned} \delta_{\mathcal{X}}^{(3,0)} \mathcal{Q} := & \delta_{\mathcal{X}}^{(3,0)} Q - 3 \mathcal{L}_{(1,0)\mathcal{X}X} \delta_{\mathcal{X}}^{(2,0)} Q - 3 \left\{ \mathcal{L}_{(2,0)\mathcal{X}X} - \mathcal{L}_{(1,0)\mathcal{X}X}^2 \right\} \delta_{\mathcal{X}}^{(1,0)} Q \\ & - \left\{ \mathcal{L}_{(3,0)\mathcal{X}X} - 3 \mathcal{L}_{(1,0)\mathcal{X}X} \mathcal{L}_{(2,0)\mathcal{X}X} + \mathcal{L}_{(1,0)\mathcal{X}X}^3 \right\} Q_0, \end{aligned} \quad (4.49)$$

$$\begin{aligned} \delta_{\mathcal{X}}^{(2,1)} \mathcal{Q} := & \delta_{\mathcal{X}}^{(2,1)} Q - 2 \mathcal{L}_{(1,0)\mathcal{X}X} \delta_{\mathcal{X}}^{(1,1)} Q - \mathcal{L}_{(1,0)\mathcal{X}X} \delta_{\mathcal{X}}^{(2,0)} Q \\ & - \left\{ \mathcal{L}_{(2,0)\mathcal{X}X} - \mathcal{L}_{(1,0)\mathcal{X}X}^2 \right\} \delta_{\mathcal{X}}^{(0,1)} Q \\ & - 2 \left\{ \mathcal{L}_{(1,1)\mathcal{X}X} - \frac{1}{2} \mathcal{L}_{(1,0)\mathcal{X}X} \mathcal{L}_{(0,1)\mathcal{X}X} - \frac{1}{2} \mathcal{L}_{(0,1)\mathcal{X}X} \mathcal{L}_{(1,0)\mathcal{X}X} \right\} \delta_{\mathcal{X}}^{(1,0)} Q \\ & - \left\{ \mathcal{L}_{(2,1)\mathcal{X}X} - 2 \mathcal{L}_{(1,0)\mathcal{X}X} \mathcal{L}_{(1,1)\mathcal{X}X} - \mathcal{L}_{(0,1)\mathcal{X}X} \mathcal{L}_{(2,0)\mathcal{X}X} \right. \\ & \quad \left. + \mathcal{L}_{(1,0)\mathcal{X}X} \mathcal{L}_{(0,1)\mathcal{X}X} \mathcal{L}_{(1,0)\mathcal{X}X} \right\} Q_0, \end{aligned} \quad (4.50)$$

$$\begin{aligned} \delta_{\mathcal{X}}^{(1,2)} \mathcal{Q} := & \delta_{\mathcal{X}}^{(1,2)} Q - 2 \mathcal{L}_{(0,1)\mathcal{X}X} \delta_{\mathcal{X}}^{(1,1)} Q - \mathcal{L}_{(1,0)\mathcal{X}X} \delta_{\mathcal{X}}^{(0,2)} Q \\ & - \left\{ \mathcal{L}_{(0,2)\mathcal{X}X} - \mathcal{L}_{(0,1)\mathcal{X}X}^2 \right\} \delta_{\mathcal{X}}^{(1,0)} Q \\ & - 2 \left\{ \mathcal{L}_{(1,1)\mathcal{X}X} - \frac{1}{2} \mathcal{L}_{(1,0)\mathcal{X}X} \mathcal{L}_{(0,1)\mathcal{X}X} - \frac{1}{2} \mathcal{L}_{(0,1)\mathcal{X}X} \mathcal{L}_{(1,0)\mathcal{X}X} \right\} \delta_{\mathcal{X}}^{(0,1)} Q \\ & - \left\{ \mathcal{L}_{(1,2)\mathcal{X}X} - 2 \mathcal{L}_{(0,1)\mathcal{X}X} \mathcal{L}_{(1,1)\mathcal{X}X} - \mathcal{L}_{(1,0)\mathcal{X}X} \mathcal{L}_{(0,2)\mathcal{X}X} \right. \\ & \quad \left. + \mathcal{L}_{(0,1)\mathcal{X}X} \mathcal{L}_{(1,0)\mathcal{X}X} \mathcal{L}_{(0,1)\mathcal{X}X} \right\} Q_0, \end{aligned} \quad (4.51)$$

$$\begin{aligned} \delta_{\mathcal{X}}^{(0,3)} \mathcal{Q} := & \delta_{\mathcal{X}}^{(0,3)} Q - 3 \mathcal{L}_{(0,1)\mathcal{X}X} \delta_{\mathcal{X}}^{(0,2)} Q - 3 \left\{ \mathcal{L}_{(0,2)\mathcal{X}X} - \mathcal{L}_{(0,1)\mathcal{X}X}^2 \right\} \delta_{\mathcal{X}}^{(0,1)} Q \\ & - \left\{ \mathcal{L}_{(0,3)\mathcal{X}X} - 3 \mathcal{L}_{(0,1)\mathcal{X}X} \mathcal{L}_{(0,2)\mathcal{X}X} + \mathcal{L}_{(0,1)\mathcal{X}X}^3 \right\} Q_0. \end{aligned} \quad (4.52)$$

Straightforward calculations using the gauge transformation rules (3.30)–(3.38), (4.13), (4.19), (4.24), (4.29) and (4.40)–(4.43) show that these variables $\delta_{\mathcal{X}}^{(p,q)} \mathcal{Q}$ are gauge invariant.

§5. Summary and Discussions

In this paper, we have presented the procedure to find gauge invariant variables of two-parameter nonlinear metric and matter perturbations. To describe this procedure, we have assumed the existence of the analogous procedure for linear perturba-

tions. As emphasized in the main text, the decomposition of the linear perturbation of the metric into gauge invariant and gauge variant parts is non-trivial. It depends crucially on the background spacetime. However, if we assume the existence of this procedure, we can always define the gauge invariant variables for higher order metric and matter perturbations.

The procedure presented above is summarized as follows. Suppose that gauge transformation rules for a (p, q) -order metric perturbation ${}^{(p,q)}h_{ab}$ are given by

$${}^{(p,q)}_{\mathcal{Y}}h_{ab} - {}^{(p,q)}_{\mathcal{X}}h_{ab} = F[\xi_{(p,q)}^a, \xi_{(i,j)}^a, {}^{(i,j)}_{\mathcal{X}}h_{ab}], \quad (5.1)$$

where F is a function determined by the gauge transformation rule $\mathcal{X} \rightarrow \mathcal{Y}$ of the (p, q) -order metric perturbation ${}^{(p,q)}h_{ab}$, and i and j are integers that satisfy the conditions $i \leq p$, $j \leq q$ and $i + j \neq p + q$. Further, suppose that for any i and j , we have already defined the tensor fields ${}^{(i,j)}_{\mathcal{X}}\mathcal{H}_{ab}$ and the vector fields ${}^{(i,j)}_{\mathcal{X}}X^a$ as in the main text. Then, defining the variable ${}^{(p,q)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab}$ for the $O(\lambda^p \epsilon^q)$ metric perturbation by

$${}^{(p,q)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab} := {}^{(p,q)}_{\mathcal{X}}h_{ab} + F[\xi_{(p,q)}^a, -{}^{(i,j)}_{\mathcal{X}}X^a, {}^{(i,j)}_{\mathcal{X}}h_{ab}], \quad (5.2)$$

there exists a vector field $\sigma_{(p,q)}^a$ such that the variable ${}^{(p,q)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab}$ transforms as

$${}^{(p,q)}_{\mathcal{Y}}\widehat{\mathcal{H}}_{ab} - {}^{(p,q)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab} = \mathcal{L}_{\sigma_{(p,q)}}{}^{(0)}g_{ab} \quad (5.3)$$

under the gauge transformation $\mathcal{X} \rightarrow \mathcal{Y}$. Then, using the same procedure as for linear perturbations, we can decompose ${}^{(p,q)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab}$ as

$${}^{(p,q)}_{\mathcal{X}}\widehat{\mathcal{H}}_{ab} =: {}^{(p,q)}_{\mathcal{X}}\mathcal{H}_{ab} + \nabla_a {}^{(p,q)}_{\mathcal{X}}X_b + \nabla_b {}^{(p,q)}_{\mathcal{X}}X_a, \quad (5.4)$$

where the variables ${}^{(p,q)}_{\mathcal{X}}\mathcal{H}_{ab}$ and ${}^{(p,q)}_{\mathcal{X}}X_a$ are the gauge invariant and gauge variant parts of the $O(\lambda^p \epsilon^q)$ metric perturbation, respectively. Because the gauge transformation rule for the matter perturbations $\delta^{(p,q)}Q$ is given by

$$\delta_{\mathcal{Y}}^{(p,q)}Q - \delta_{\mathcal{X}}^{(p,q)}Q = F[\xi_{(p,q)}^a, \xi_{(i,j)}^a, \delta_{\mathcal{X}}^{(i,j)}Q], \quad (5.5)$$

the corresponding gauge invariant variables $\delta_{\mathcal{X}}^{(p,q)}\mathcal{Q}$ are defined by

$$\delta_{\mathcal{X}}^{(p,q)}\mathcal{Q} = \delta_{\mathcal{X}}^{(p,q)}Q + F[-{}^{(p,q)}_{\mathcal{X}}X^a, -{}^{(i,j)}_{\mathcal{X}}X^a, \delta_{\mathcal{X}}^{(i,j)}Q]. \quad (5.6)$$

A procedure similar to that presented here for second order perturbations in the one-parameter case was previously obtained by Campanelli and Lousto.²³⁾ They applied that procedure to second order perturbations of a Kerr black hole. We have confirmed their procedure up to third order in the two-parameter case. Though the gauge transformation rule for the perturbations of arbitrary order is not yet known, we conjecture that the procedure considered here is applicable to arbitrary order perturbations. We also believe that this procedure can be confirmed by induction, once the gauge transformation rule for an arbitrary order is obtained. We leave this for a future work.

In addition to the interesting mathematical framework, it is also interesting to apply it to the astrophysical systems, such as oscillating relativistic rotating stars. Many astrophysical systems can be described well by perturbation theory with two parameters. One merit of applying the procedure presented here to such systems is the gauge ambiguities are removed. When we apply this procedure to oscillating stars, a careful analysis is necessary to properly treat the boundary conditions at the surface of the star and the displacement of this surface. Similar situations are considered in previous papers coauthored by the present author.²⁴⁾ In those papers, a particular gauge fixing is necessary to match the perturbative solutions at the boundary of the surface of the matter distribution when we construct global solutions and when we define the perturbative displacement of the matter surface. Similar problems also arise in the perturbative analysis of spacetimes with boundaries, such as brane worlds.²⁵⁾ In the investigation of these situations, the gauge transformation rules derived in BGS2003 and the gauge invariant variables defined here become powerful tools. Because of their applicability to various situations, we also expect that the techniques developed here will play a key role in progress of theoretical physics.

Acknowledgements

We would like to thank to Prof. Minoru Omote (Keio University) for his continuous encouragement.

Appendix A

— *Equivalence with the Representation of Bruni et al.* —

In this appendix, we derive the representation of the coefficients of the formal Taylor expansion (2.3) of the pull-back of a diffeomorphism in terms of the suitable derivative operators $\mathcal{L}_{(p,q)}$. As mentioned in the main text, for each of these operators, there is a vector field such that the operators satisfy Eq. (2.13). The existence of these vector fields is guaranteed by the fact that the operator $\mathcal{L}_{(p,q)}$ of each order satisfies the Leibniz rule. From this fact, the definitions of the derivative operators (2.4)–(2.12) are obtained. As shown in the Appendix in BGS2003, the representation of the Taylor expansion of $\Phi_{\lambda,\epsilon}^* f$ for an arbitrary function f can be extended to that for an arbitrary tensor field Q on \mathcal{M} . Therefore, in this appendix, we only consider the Taylor expansion of the pull-back $\Phi_{\lambda,\epsilon}^* f$ for an arbitrary scalar function $f \in \mathcal{F}(\mathcal{M})$:

$$\Phi_{\lambda,\epsilon}^* f = \sum_{k,k'=0}^{\infty} \frac{\lambda^k \epsilon^{k'}}{k!k'!} \left\{ \frac{\partial^{k+k'}}{\partial \lambda^k \partial \epsilon^{k'}} \Phi_{\lambda,\epsilon}^* f \right\}_{\lambda=\epsilon=0}, \quad (\text{A.1})$$

where $\mathcal{F}(\mathcal{M})$ denotes the algebra of C^∞ functions on \mathcal{M} .

Although the operators $\partial/\partial\lambda$ and $\partial/\partial\epsilon$ in the bracket $\{*\}_{\lambda=\epsilon=0}$ of Eq. (A.1) are

simply symbolic notation, we stipulate the properties

$$\begin{aligned} \left\{ \frac{\partial^{n+1}}{\partial \lambda^{n+1}} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} &= \left\{ \frac{\partial}{\partial \lambda} \left(\frac{\partial^n}{\partial \lambda^n} \Phi_{\lambda, \epsilon}^* f \right) \right\}_{\lambda=\epsilon=0} \\ &= \left\{ \frac{\partial^n}{\partial \lambda^n} \left(\frac{\partial}{\partial \lambda} \Phi_{\lambda, \epsilon}^* f \right) \right\}_{\lambda=\epsilon=0}, \end{aligned} \quad (\text{A}\cdot 2)$$

$$\begin{aligned} \left\{ \frac{\partial^{n+1}}{\partial \epsilon^{n+1}} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} &= \left\{ \frac{\partial}{\partial \epsilon} \left(\frac{\partial^n}{\partial \epsilon^n} \Phi_{\lambda, \epsilon}^* f \right) \right\}_{\lambda=\epsilon=0} \\ &= \left\{ \frac{\partial^n}{\partial \epsilon^n} \left(\frac{\partial}{\partial \epsilon} \Phi_{\lambda, \epsilon}^* f \right) \right\}_{\lambda=\epsilon=0}, \end{aligned} \quad (\text{A}\cdot 3)$$

$$\begin{aligned} \left\{ \frac{\partial^2}{\partial \lambda \partial \epsilon} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} &= \left\{ \frac{\partial}{\partial \lambda} \left(\frac{\partial}{\partial \epsilon} \Phi_{\lambda, \epsilon}^* f \right) \right\}_{\lambda=\epsilon=0} \\ &= \left\{ \frac{\partial}{\partial \epsilon} \left(\frac{\partial}{\partial \lambda} \Phi_{\lambda, \epsilon}^* f \right) \right\}_{\lambda=\epsilon=0}, \end{aligned} \quad (\text{A}\cdot 4)$$

$$\left\{ \frac{\partial}{\partial \lambda} (\Phi_{\lambda, \epsilon}^* f)^2 \right\}_{\lambda=\epsilon=0} = \left\{ 2\Phi_{\lambda, \epsilon}^* f \frac{\partial}{\partial \lambda} (\Phi_{\lambda, \epsilon}^* f) \right\}_{\lambda=\epsilon=0}, \quad (\text{A}\cdot 5)$$

$$\left\{ \frac{\partial}{\partial \epsilon} (\Phi_{\lambda, \epsilon}^* f)^2 \right\}_{\lambda=\epsilon=0} = \left\{ 2\Phi_{\lambda, \epsilon}^* f \frac{\partial}{\partial \epsilon} (\Phi_{\lambda, \epsilon}^* f) \right\}_{\lambda=\epsilon=0} \quad (\text{A}\cdot 6)$$

for $\forall f \in \mathcal{F}(\mathcal{M})$, where n is an arbitrary finite integer. These properties imply that the operators $\partial/\partial\lambda$ and $\partial/\partial\epsilon$ are in fact not simply symbolic notation but indeed the usual partial differential operators on \mathbb{R}^2 . We note that the properties (A·5) and (A·6) are the Leibniz rules, which play important roles when we derive the representation of the Taylor expansion (A·1) in terms of suitable Lie derivatives.

We can easily show that the derivative operators $\mathcal{L}_{(1,0)}$ and $\mathcal{L}_{(0,1)}$, defined by (2·4) and (2·5), respectively, satisfy the Leibniz rule

$$\mathcal{L}_{(p,q)} f^2 = 2f \mathcal{L}_{(p,q)} f \quad (\text{A}\cdot 7)$$

due to the properties (A·5) and (A·6). In the higher order coefficients of the expansion (A·1), the properties (A·5), (A·6) and (A·7) lead to non-trivial combinations of the linear operators. In BGS2003, it is commented that the representations of the higher order coefficients is not unique, and the following combinations are derived:

$$\left\{ \frac{\partial}{\partial \lambda} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} = \mathcal{L}_{(1,0)} f, \quad (\text{A}\cdot 8)$$

$$\left\{ \frac{\partial}{\partial \epsilon} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} = \mathcal{L}_{(0,1)} f, \quad (\text{A}\cdot 9)$$

$$\left\{ \frac{\partial^2}{\partial \lambda^2} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} = \mathcal{L}_{(2,0)} f + \mathcal{L}_{(1,0)}^2 f, \quad (\text{A}\cdot 10)$$

$$\left\{ \frac{\partial^2}{\partial \lambda \partial \epsilon} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} = \mathcal{L}_{(1,1)} f + (\epsilon_0 \mathcal{L}_{(1,0)} \mathcal{L}_{(0,1)} + \epsilon_1 \mathcal{L}_{(0,1)} \mathcal{L}_{(1,0)}) f, \quad (\text{A}\cdot 11)$$

$$\left\{ \frac{\partial^2}{\partial \epsilon^2} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} = \mathcal{L}_{(0,2)} f + \mathcal{L}_{(0,1)}^2 f, \quad (\text{A}\cdot 12)$$

$$\left\{ \frac{\partial^3}{\partial \lambda^3} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} = \mathcal{L}_{(3,0)} f + 3\mathcal{L}_{(1,0)} \mathcal{L}_{(2,0)} f + \mathcal{L}_{(1,0)}^3 f, \quad (\text{A}\cdot 13)$$

$$\begin{aligned} \left\{ \frac{\partial^3}{\partial \lambda^2 \partial \epsilon} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} &= \mathcal{L}_{(2,1)} f + 2\mathcal{L}_{(1,0)} \mathcal{L}_{(1,1)} f \\ &\quad + \mathcal{L}_{(0,1)} \mathcal{L}_{(2,0)} f + 2\epsilon_2 \mathcal{L}_{(1,0)} \mathcal{L}_{(0,1)} \mathcal{L}_{(1,0)} f \\ &\quad + (\epsilon_1 - \epsilon_2) \mathcal{L}_{(0,1)} \mathcal{L}_{(1,0)}^2 f + (\epsilon_0 - \epsilon_2) \mathcal{L}_{(1,0)}^2 \mathcal{L}_{(0,1)} f, \end{aligned} \quad (\text{A}\cdot 14)$$

$$\begin{aligned} \left\{ \frac{\partial^3}{\partial \lambda \partial \epsilon^2} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} &= \mathcal{L}_{(1,2)} f + 2\mathcal{L}_{(0,1)} \mathcal{L}_{(1,1)} f \\ &\quad + \mathcal{L}_{(1,0)} \mathcal{L}_{(0,2)} f + 2\epsilon_3 \mathcal{L}_{(0,1)} \mathcal{L}_{(1,0)} \mathcal{L}_{(0,1)} f \\ &\quad + (\epsilon_0 - \epsilon_3) \mathcal{L}_{(1,0)} \mathcal{L}_{(0,1)}^2 f + (\epsilon_1 - \epsilon_3) \mathcal{L}_{(0,1)}^2 \mathcal{L}_{(1,0)} f, \end{aligned} \quad (\text{A}\cdot 15)$$

$$\left\{ \frac{\partial^3}{\partial \epsilon^3} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} = \mathcal{L}_{(0,3)} f + 3\mathcal{L}_{(0,1)} \mathcal{L}_{(0,2)} f + \mathcal{L}_{(0,1)}^3 f. \quad (\text{A}\cdot 16)$$

Here, the parameters ϵ_i ($i = 0, 1, 2, 3$) are constants that satisfy the condition

$$\epsilon_0 + \epsilon_1 = 1. \quad (\text{A}\cdot 17)$$

These parameters result from the fact that the representation of the higher order coefficients in terms of the derivative operators is not unique.

As emphasized in BGS2003, the parameters ϵ_i in the representations (A·8)–(A·16) are not essential. Each operator $\mathcal{L}_{(p,q)}$ is regarded as the Lie derivative with respect to the vector field $\xi_{(p,q)}^a$ as mentioned above (see Eq. (2·13)). Once we obtain the representation of $\mathcal{L}_{(p,q)}$ in terms of the Lie derivative, the parameters ϵ_i are always eliminated through the replacement of the vector field. As a result, we obtain the “canonical representation” (2·14) in the main text. Therefore, the “canonical representation” (2·14) of the Taylor expansion with two infinitesimal parameters is equivalent to that in BGS2003 as shown below.

To show this, it is necessary to give an explicit derivation of the representations (A·8)–(A·16). The derivations of these representations are done recursively from lower order representations. Because the derivation of each representation is similar, it is enough to present the explicit derivation of the representation of the coefficients of $O(\lambda^2 \epsilon)$, and we start from the point where the lower order representations (A·8)–(A·13) are already given. It is obvious that the coefficient of $O(\lambda^2 \epsilon)$ in the expansion (A·1) includes a linear combination of the following terms:

$$\begin{aligned} &\mathcal{L}_{(0,1)} \mathcal{L}_{(2,0)} f, \quad \mathcal{L}_{(2,0)} \mathcal{L}_{(0,1)} f, \quad \mathcal{L}_{(1,0)} \mathcal{L}_{(1,1)} f, \quad \mathcal{L}_{(1,1)} \mathcal{L}_{(1,0)} f, \\ &\mathcal{L}_{(0,1)} \mathcal{L}_{(1,0)} \mathcal{L}_{(1,0)} f, \quad \mathcal{L}_{(1,0)} \mathcal{L}_{(0,1)} \mathcal{L}_{(1,0)} f, \quad \mathcal{L}_{(1,0)} \mathcal{L}_{(1,0)} \mathcal{L}_{(0,1)} f. \end{aligned} \quad (\text{A}\cdot 18)$$

Then, we start from the following form of the derivative operator $\mathcal{L}_{(2,1)}$:

$$\begin{aligned} \mathcal{L}_{(2,1)} f &:= \left\{ \frac{\partial^3}{\partial \lambda^2 \partial \epsilon} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} \\ &\quad + p_1 \mathcal{L}_{(0,1)} \mathcal{L}_{(2,0)} f + p_2 \mathcal{L}_{(1,0)} \mathcal{L}_{(1,1)} f \\ &\quad + p_3 \mathcal{L}_{(0,1)} \mathcal{L}_{(1,0)} \mathcal{L}_{(1,0)} f + p_4 \mathcal{L}_{(1,0)} \mathcal{L}_{(0,1)} \mathcal{L}_{(1,0)} f + p_5 \mathcal{L}_{(1,0)} \mathcal{L}_{(1,0)} \mathcal{L}_{(0,1)} f \\ &\quad + p_6 \mathcal{L}_{(2,0)} \mathcal{L}_{(0,1)} f + p_7 \mathcal{L}_{(1,1)} \mathcal{L}_{(1,0)} f. \end{aligned} \quad (\text{A}\cdot 19)$$

Following the argument in BGS2003, we choose

$$p_6 = p_7 = 0. \quad (\text{A}\cdot 20)$$

This choice is always possible. The lower order derivative operators $\mathcal{L}_{(p,q)}$ are regarded as the Lie derivative with appropriate generators $\xi_{(p,q)}^a$ as in Eq. (2.13) and the first term on the second line and the first term on the fourth line in the right-hand side of Eq. (A.19) are given by

$$\begin{aligned} & p_1 \mathcal{L}_{(0,1)} \mathcal{L}_{(2,0)} f + p_6 \mathcal{L}_{(2,0)} \mathcal{L}_{(0,1)} f \\ &= (p_1 + p_6) \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(2,0)}} f + \mathcal{L}_{p_6 [\xi_{(2,0)}, \xi_{(0,1)}]} f. \end{aligned} \quad (\text{A}\cdot 21)$$

Because, as we will show, $\mathcal{L}_{(2,1)} = \mathcal{L}_{\xi_{(2,1)}}$ even if $p_6 \neq 0$, we can always choose $p_6 = 0$ by making the replacement

$$p_1 + p_6 \rightarrow p_1, \quad \xi_{(2,1)}^a + p_6 [\xi_{(2,0)}, \xi_{(0,1)}]^a \rightarrow \xi_{(2,1)}^a, \quad (\text{A}\cdot 22)$$

without loss of generality. The same argument can be applied to the parameter p_7 . Therefore, we may choose $p_6 = p_7 = 0$, without loss of generality. We note that similar arguments can be applied to the cases of the parameter p_3 , p_4 and p_5 . We can fix these parameters by using the replacement of the vector field $\xi_{(2,1)}^a$. However, we do not proceed with this argument here, because we have confirmed that the representation in BGS2003, i.e. (A.8)–(A.16) in this paper, and Eqs. (2.4)–(2.12) are equivalent, at least up to fourth order.

To guarantee the Leibniz rule for the derivative operator $\mathcal{L}_{(2,1)}$, we first consider the operation

$$\left\{ \frac{\partial^3}{\partial \lambda^2 \partial \epsilon} (\Phi_{\lambda, \epsilon}^* f)^2 \right\}_{\lambda=\epsilon=0} \quad \forall f \in \mathcal{F}(\mathcal{M}). \quad (\text{A}\cdot 23)$$

Using Eqs. (A.2)–(A.6), we obtain

$$\begin{aligned} \left\{ \frac{\partial^3}{\partial \lambda^2 \partial \epsilon} (\Phi_{\lambda, \epsilon}^* f)^2 \right\}_{\lambda=\epsilon=0} &= 2 \left\{ \frac{\partial^2}{\partial \lambda^2} (\Phi_{\lambda, \epsilon}^* f) \right\}_{\lambda=\epsilon=0} \left\{ \frac{\partial}{\partial \epsilon} (\Phi_{\lambda, \epsilon}^* f) \right\}_{\lambda=\epsilon=0} \\ &\quad + 4 \left\{ \frac{\partial}{\partial \lambda} (\Phi_{\lambda, \epsilon}^* f) \right\}_{\lambda=\epsilon=0} \left\{ \frac{\partial^2}{\partial \lambda \partial \epsilon} (\Phi_{\lambda, \epsilon}^* f) \right\}_{\lambda=\epsilon=0} \\ &\quad + 2f \left\{ \frac{\partial^3}{\partial \lambda^2 \partial \epsilon} (\Phi_{\lambda, \epsilon}^* f) \right\}_{\lambda=\epsilon=0}. \end{aligned} \quad (\text{A}\cdot 24)$$

Substituting Eqs. (A.8)–(A.12), (A.19) and (A.20) into Eq. (A.24), we obtain the representation of Eq. (A.23), which includes the term $2f \mathcal{L}_{(2,1)} f$. On the other hand, a direct calculation from Eq. (A.19) with Eqs.(A.20) gives the representation of Eq. (A.23) which includes the term $\mathcal{L}_{(2,1)} f^2$. To obtain this second representation of Eq. (A.23), we can use the Leibniz rules for the derivative operators, except for $\mathcal{L}_{(2,1)}$, because the Leibniz rules for the lower order operators can be demonstrated by arguments similar to that given here, and these can be confirmed before applying the arguments for the operator $\mathcal{L}_{(2,1)}$. From these two representations of Eq. (A.23),

we obtain

$$\begin{aligned}
\mathcal{L}_{(2,1)}(f^2) - 2f\mathcal{L}_{(2,1)}f &= 2(p_1 + 1)(\mathcal{L}_{(0,1)}f)(\mathcal{L}_{(2,0)}f) \\
&\quad + 2(p_2 + 2)(\mathcal{L}_{(1,0)}f)(\mathcal{L}_{(1,1)}f) \\
&\quad + 2(p_3 + p_4 + p_5 + 1)(\mathcal{L}_{(0,1)}f)(\mathcal{L}_{(1,0)}^2f) \\
&\quad + 2(p_4 + 2p_3 + 2\epsilon_1)(\mathcal{L}_{(0,1)}\mathcal{L}_{(1,0)}f)(\mathcal{L}_{(1,0)}f) \\
&\quad + 2(p_4 + 2p_5 + 2\epsilon_0)(\mathcal{L}_{(1,0)}\mathcal{L}_{(0,1)}f)(\mathcal{L}_{(1,0)}f). \quad (\text{A}\cdot 25)
\end{aligned}$$

This shows that the derivative operator $\mathcal{L}_{(2,1)}$ satisfies the Leibniz rule $\mathcal{L}_{(2,1)}(f^2) = 2f\mathcal{L}_{(2,1)}f$ for an arbitrary function $f \in \mathcal{F}(\mathcal{M})$ iff

$$p_1 = -1, \quad p_2 = -2, \quad p_3 = -(\epsilon_1 - \epsilon_2), \quad p_5 = -(\epsilon_0 - \epsilon_2), \quad (\text{A}\cdot 26)$$

where ϵ_0 and ϵ_1 appear from the representation of $\mathcal{L}_{(1,1)}$ through the substitution of Eq. (A.11) into Eq. (A.24), and ϵ_2 is an arbitrary parameter that is not determined by the Leibniz rule for $\mathcal{L}_{(2,1)}$. Thus, the representation (A.14) is obtained.

Finally, we show that the undetermined parameter ϵ_i ($i = 0, \dots, 3$) can be eliminated through the replacement of the vector fields $\xi_{(p,q)}^a$. First, we consider the derivative operator (A.11) of $O(\lambda\epsilon)$. Then, using Eq. (A.17), the replacement

$$\xi_{(1,1)}'^a = \xi_{(1,1)}^a + \frac{1}{2}(\epsilon_0 - \epsilon_1)[\xi_{(1,0)}, \xi_{(0,1)}]^a, \quad (\text{A}\cdot 27)$$

leads

$$\left\{ \frac{\partial^2}{\partial \lambda \partial \epsilon} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} = \mathcal{L}_{\xi_{(1,1)}'} f + \left(\frac{1}{2} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} + \frac{1}{2} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \right) f. \quad (\text{A}\cdot 28)$$

This implies that the parameters ϵ_0 and ϵ_1 should be chosen so that

$$\epsilon_0 = \epsilon_1 = \frac{1}{2} \quad (\text{A}\cdot 29)$$

without loss of generality. Similarly, the replacements of the generators $\xi_{(2,1)}$ and $\xi_{(1,2)}$,

$$\xi_{(2,1)}'^a := \xi_{(2,1)}^a + (\epsilon_1 - \epsilon_2)[\xi_{(1,0)}, [\xi_{(1,0)}, \xi_{(0,1)}]]^a, \quad (\text{A}\cdot 30)$$

$$\xi_{(1,2)}'^a := \xi_{(1,2)}^a + (\epsilon_1 - \epsilon_3)[\xi_{(0,1)}, [\xi_{(0,1)}, \xi_{(1,0)}]]^a, \quad (\text{A}\cdot 31)$$

lead to

$$\begin{aligned}
\left\{ \frac{\partial^3}{\partial \lambda^2 \partial \epsilon} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} &= \mathcal{L}_{\xi_{(2,1)}'} + 2\mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(1,1)}'} \\
&\quad + \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(2,0)}} + \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}}, \quad (\text{A}\cdot 32)
\end{aligned}$$

$$\begin{aligned}
\left\{ \frac{\partial^3}{\partial \lambda \partial \epsilon^2} \Phi_{\lambda, \epsilon}^* f \right\}_{\lambda=\epsilon=0} &= \mathcal{L}_{\xi_{(1,2)}'} + 2\mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,1)}'} \\
&\quad + \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,2)}} + \mathcal{L}_{\xi_{(0,1)}} \mathcal{L}_{\xi_{(1,0)}} \mathcal{L}_{\xi_{(0,1)}}. \quad (\text{A}\cdot 33)
\end{aligned}$$

These show that the parameters ϵ_2 and ϵ_3 should be chosen so that

$$\epsilon_2 = \epsilon_3 = \frac{1}{2} \quad (\text{A.34})$$

without loss of generality. Thus, the undetermined parameters in the representation derived in BGS2003 are eliminated through the replacement of generators $\xi_{(p,q)}^a$, and the representation of the Taylor expansion in BGS2003 is equivalent to (2.14) in the main text. This also implies that the representation of the Taylor expansion of the pull-back $\Phi_{\lambda,\epsilon}^* Q$ is not unique, but this non-uniqueness causes no serious problems.

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